



elmer
ICE



EGU 2013 – Elmer/Ice Splinter Meeting

New Developments for Elmer/Ice

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Contents

- New `elmerice` installation package
- New features for glaciological simulations:
 - New implementation of Glen's flow law
 - Internal extrusion
 - Block pre-conditioner
 - Mass-conserving normals
- Preliminary results AAIS



Elmer and Elmer/Ice

- Elmer ~300 000 lines of mixed F90, C and C++ code
- Elmer/Ice ~20 000 lines add-on to Elmer
- Main developments in algorithms, parallel performance enhancement driven by Elmer
 - Most work is done within CSC
 - Current developments:
 - OpenMP multi-threading, hybrid MPI-OpenMP
 - Intel PSI porting (many-core systems)
 - Sliding mesh boundaries

Elmer/Ice installation package

- SourceForge (SF):

<http://sourceforge.net/projects/elmerfem/>

- New SVN address:

- Checkout without SF-ID:

```
svn co svn://svn.code.sf.net/p/elmerfem/code/trunk/
```

- Checkout with SF-ID (needs password):

```
svn checkout --username=sflogin  
  svn+ssh://sflogin@svn.code.sf.net/p/elmerfem/code  
  /trunk
```

- Elmer/Ice is residing in a sub-directory: trunk/elmerice

Elmer/Ice installation package

- Prerequisites:
 - existing Elmer installation
 - UNIX/Linux system
 - (GNU)-make
- Either define `ELMERICE_HOME` as the installation path
- Preferably: have `ELMER_HOME` defined and Elmer/Ice then is installed in `$(ELMER_HOME)/share/elmersolver`
 - Mind that you have to have rights to write the `$(ELMER_HOME)-tree`

Elmer/Ice installation package

- Remove leftovers from previous builds:
`make purge`
- Compile: `make compile`
- Install: `make install`
 - If you need to use `sudo` option, use `-E` to copy the environment.

Elmer/Ice installation package

➤ Installation of two additional shared objects:

- `ElmerIceSolvers.so`: contains all solver subroutines (physical models)
- `ElmerIceUSF.so`: contains all user functions (boundary conditions, etc.)

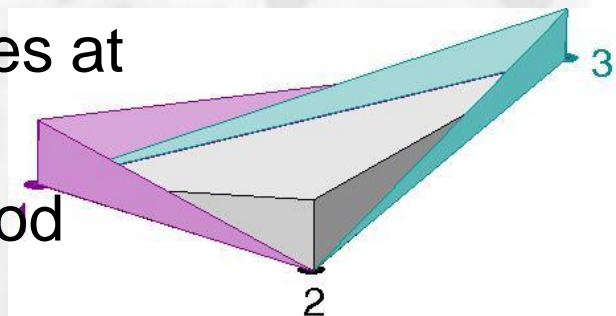
➤ Call syntax:

- Procedure = File "ElmerIceSolvers"
"NameSolver"
- Description of all Solvers on Wiki page
<http://elmerice.elmerfem.org/wiki/doku.php?id=solvers>

Glen's flow law

$$\eta = \frac{1}{2} (EA)^{-1/n} \dot{\epsilon}_e^{(1-n)/n} .$$

- Until recently:
 - used the Elmer built-in **power law** and provided the temperature-dependent part at the nodes only (MATC function)
- New Viscosity law in Elmer:
 - Viscosity model **Glen** in Material section
 - Evaluates all variable dependencies at integration points
 - Increased stability – Newton method works
 - Documentation in Elmer/Ice Wiki





Glen's flow law

$$\eta = \frac{1}{2}(EA)^{-1/n} \dot{\epsilon}_e^{(1-n)/n}.$$

Viscosity Model = String "Glen"

!Viscosity has to be set to a dummy value

! Use "sane" value for ParStokes

Viscosity = Real

\$1.0E13*365.25*24*3600*1.0E-06

Glen Exponent = Real 3.0

Critical Shear Rate = Real (1.0e-10 - T')

! Rate factors

Rate Factor 1 = Real 1.258e13

Rate Factor 2 = Real 6.046e28

Activation Energy 1 = Real 60e3

Activation Energy 2 = Real 139e3

Glen Enhancement Factor = Real 1.0

Glen's flow law

$$A(T) = A_0 \exp(-Q/R(T_0 - T'))$$

! the temperature to switch between the

! two regimes in the flow law

Limit Temperature = Real -10.0

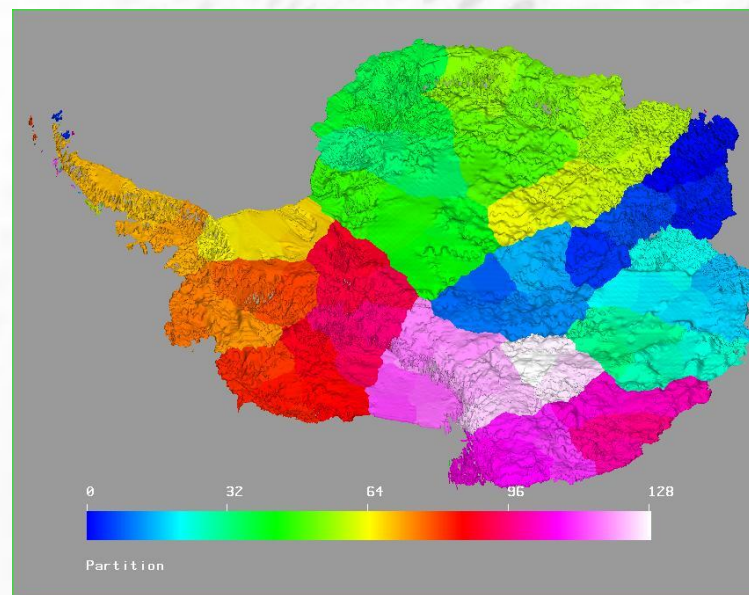
Temperature Field Variable = String "Temp
Homologous"

! In case there is no temperature variable

!Constant Temperature = Real -10.0

Internal mesh extrusion

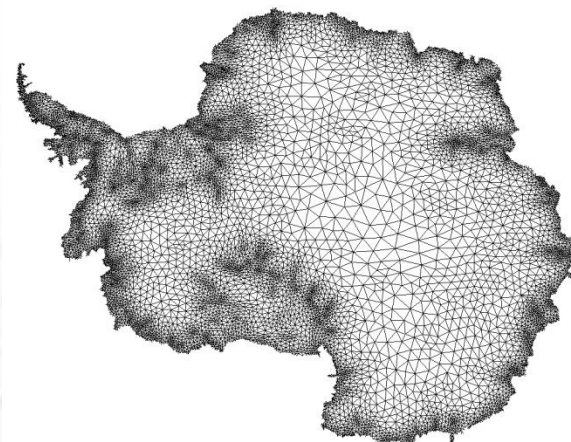
- Until recently:
 - Build 2D footprint (optimize footprint)
 - Extrude externally (e.g. ExtrudeMesh)
 - Split resulting 3D mesh into partitions
 - Disadvantages:
 - 3D bottleneck
 - limited in size
 - Not able to utilize vertical columns



Internal mesh extrusion

➤ New approach:

- Create footprint (like earlier)
- Partition footprint
- The rest is done inside Elmer



➤ Internal extrusion:

- Keyword in **Simulation**:
Extruded Mesh Levels=10
- This extrudes the footprint (here in 10 levels) to unit-height
- Still need to prescribe the bedrock and surface topography

Internal mesh extrusion

- Reading NetCDF information:
 - **GridDataReader** Under elmerice/netcdf2 (earlier under misc-tree)
 - Naturally, needs working NetCDF installation

Solver 1

```
Equation = "DataReader"  
Exec Solver = "Before All"  
Procedure = "GridDataReader" "GridDataReader"  
Filename = File "netcdf/ALBMAPv1.nc"  
X Name = String "x1"  
Y Name = String "y1"  
!--- Interpolation variable tolerances  
X Epsilon = Real 1.0e-2  
Y Epsilon = Real 1.0e-2  
Epsilon Time = Real 0.01  
!---- offsets and stretching  
Interpolation Bias = Real 0.0  
Interpolation Multiplier = Real 1.0
```

Internal mesh extrusion

➤ Reading NetCDF information:

```
Is Time Counter = Logical True
```

```
Variable 1 = usrf ! upper surface
```

```
Variable 2 = lsrf2 ! lower surface
```

```
Valid Min Value 1 = Real 0.0
```

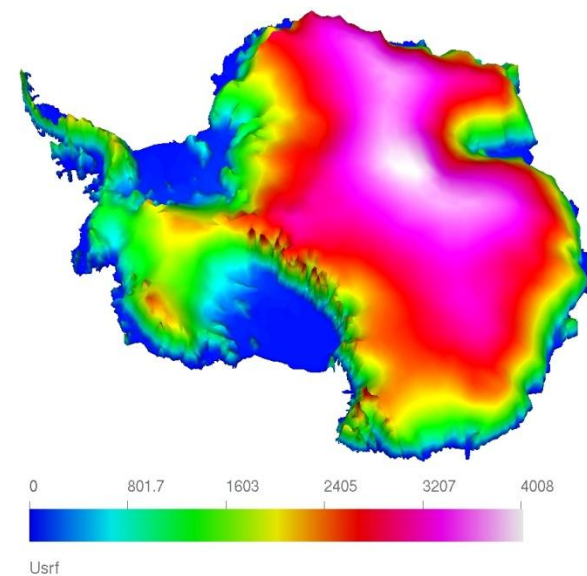
```
Valid Min Value 2 = Real -3000.0
```

```
! Scales the Elmer grid to match the
```

```
! NetCDF grid - usually not a good idea
```

```
Enable Scaling = Logical False
```

```
End
```



Internal mesh extrusion

➊ Mapping the surfaces: StructuredMeshMapper

Solver 5

Exec Solver = "Before Simulation"

Equation = "MapCoordinate"

Procedure = "StructuredMeshMapper" "StructuredMeshMapper"

Active Coordinate = Integer 3

Dot Product Tolerance = Real 0.0001

Minimum Mesh Height = Real 100.0

End

Boundary Condition 1

Name = "Bottom"

Bottom Surface = Equals lsrf2

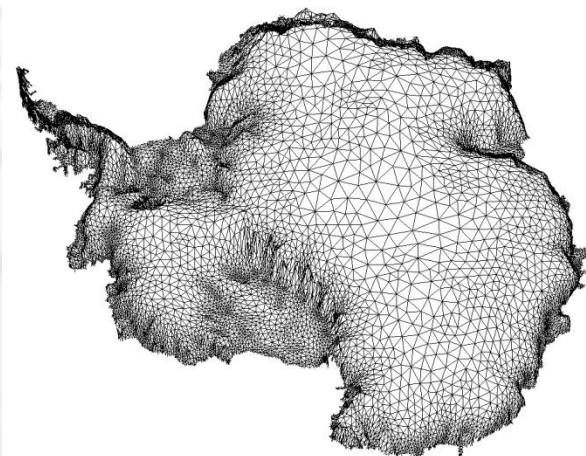
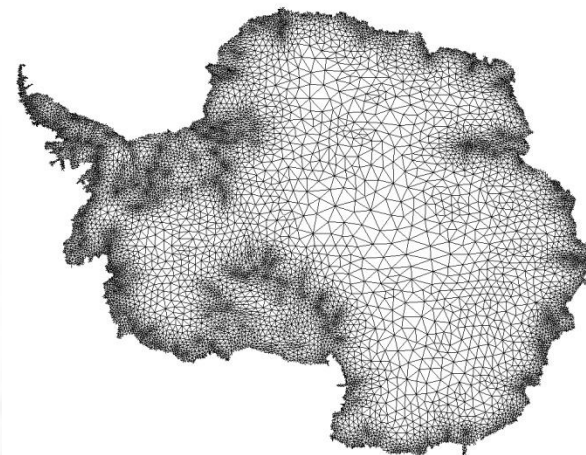
End

Boundary Condition 3

Name = "Surface"

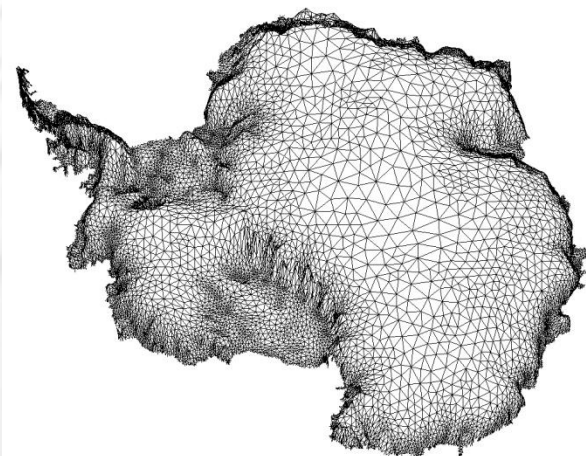
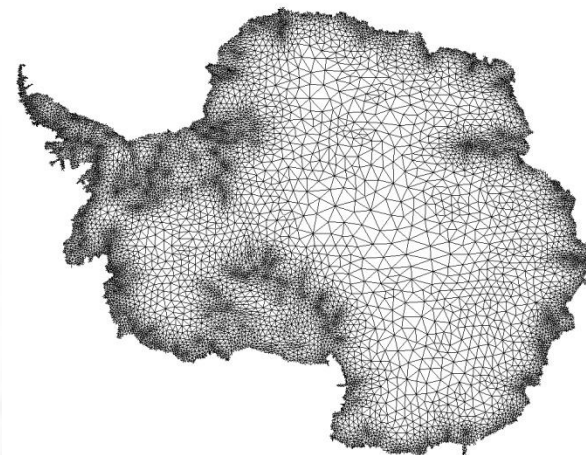
Top Surface = Equals usrf

End



Internal mesh extrusion

- Mapping the surfaces:
StructuredMeshMapper
- Can be used also in prognostic runs:
 - Uses free surface variable for mapping the upper surface
 - Also possible to be used for isostasy at bedrock
 - Only vertical shifting of mesh, no solution of pseudo-elastic problem; **stability!**



Block pre-conditioner

- Stokes equation:
 - Saddle-point problem: needs stabilization
 - Strong spatial variation/low-shear rate singularity of viscosity: bad condition number
- Until recently: direct solution
 - MUMPS
 - Strong limits due to memory
 - Not good scalability above ~100 processes
 - Need Krylov subspace solver to work

Block pre-conditioner

- Stokes equation:
$$K \cdot x = \begin{pmatrix} A & B^{(T)} \\ B & C \end{pmatrix} \cdot \begin{pmatrix} v \\ p \end{pmatrix} = f$$
 - A is similar to an elasticity problem (Navier-equation)
 - B is the discretized negative divergence
 - C results from stabilization
- Strategy: use pre-conditioner and solve with Krylov-subspace method (in our case GCR)

Block pre-conditioner

- **GCR:** $\mathbf{x} = \mathbf{x}_0 + \sum_{i=1}^k \alpha_i \mathbf{s}_i$
 - Builds solution space from initial solution \mathbf{x}_0 and a series of directional updates \mathbf{s}_i
 - Minimizes the residual $\|\mathbf{r}\| = \|\mathbf{K} \cdot \mathbf{x} - \mathbf{f}\| \rightarrow \min$
- **Block pre-conditioner:**
 - We use \mathbf{P} instead of \mathbf{K}
$$\mathbf{P} = \begin{pmatrix} \mathbf{A} & \mathbf{B}^{(\text{T})} \\ \mathbf{0} & \mathbf{M} \end{pmatrix}$$
to get directions: $\mathbf{P} \cdot \mathbf{s}_{i+1} = \mathbf{r}_i$
 - \mathbf{M} is a mass-matrix scaled with the element-wise fluidity (instead of exact pressure-Schur complement)

Block pre-conditioner

➤ Block pre-conditioner:

- Remaining issue: Need approximated inverse of P to get a solution of $P \cdot s_{i+1} = r_i$

$$P = \begin{pmatrix} A & B^{(T)} \\ 0 & M \end{pmatrix}$$

- Advantage: can get separate solution for A -block and M
- Elmer provides interfaces to different libraries (Hypre, Trilinos) to get this solved

Block pre-conditioner

➤ How to use it?

- Source code is in

```
trunk/fem/src/modules/ParStokes.src
```

- Copy the code to your directory (possibly rename the suffix to `.f90`, as some Fortran compilers are picky about this) and then simply compile it:

```
elmerf90 ParStokes.f90 -o  
ParStokes.so
```

- Create a dummy routine (see next slide) for the blocks and compile it:

```
elmerf90 DummySolver.f90 -o  
DummySolver.so
```

Block pre-conditioner

```
SUBROUTINE DummyRoutine ( Model, Solver, dt, TransientSimulation )
  USE DefUtils
  USE SolverUtils
  USE ElementUtils
  IMPLICIT NONE
  TYPE(Solver_t) :: Solver
  TYPE(Model_t) :: Model
  REAL(KIND=dp) :: dt
  LOGICAL :: TransientSimulation

  PRINT *, "Setting up block matrix"

END SUBROUTINE DummyRoutine
```


Block pre-conditioner

$$P = \begin{pmatrix} \mathbf{A} & \mathbf{B}^{(T)} \\ \mathbf{0} & \mathbf{M} \end{pmatrix}$$

Solver 1

```
Equation = "Velocity Preconditioning"  
Procedure = "DummyRoutine" "DummyRoutine"  
Variable = -dofs 3 "V"  
Variable Output = False  
Exec Solver = "before simulation"  
Element = "p:1 b:4"  
Bubbles in Global System = False  
Linear System Symmetric = True  
Linear System Scaling = True  
Linear System Row Equilibration = Logical False  
Linear System Solver = Iterative  
Linear System Iterative Method = BiCGStab  
Linear System Max Iterations = 250  
Linear System Preconditioning = ILU0  
Linear System Convergence Tolerance = 1.0e-6  
Linear System Abort Not Converged = False  
Skip Compute Nonlinear Change = Logical True  
Back Rotate N-T Solution = Logical False  
Linear System Timing = True
```

End

- Dummy solver, just to allocate the matrix block
- Defines the solution parameters that are taken over by ParStokes

Block pre-conditioner

Solver 2

```
Equation = "Pressure Preconditioning"  
Procedure = "DummyRoutine" "DummyRoutine"  
Variable = -dofs 1 "P"  
Variable Output = False  
Exec Solver = "before simulation"  
Element = "p:1 b:4"  
Bubbles in Global System = False  
Linear System Symmetric = True  
Linear System Scaling = True  
Linear System Solver = iterative  
Linear System Iterative Method = CG  
Linear System Max Iterations = 1000  
Linear System Convergence Tolerance = 1.0e-6  
Linear System Preconditioning = Diagonal  
Linear System Residual Output = 10  
Skip Compute Nonlinear Change = Logical True  
Back Rotate N-T Solution = Logical False Linear  
System Timing = True
```

End

$$P = \begin{pmatrix} A & B^{(T)} \\ 0 & \textcircled{M} \end{pmatrix}$$

- Dummy solver, just to allocate the matrix block
- Defines the solution parameters that are taken over by ParStokes

Block pre-conditioner

$$P = \begin{pmatrix} A & B^{(T)} \\ 0 & M \end{pmatrix}$$

Solver 3

```
Equation = "Stokes"
Procedure = "ParStokes" "StokesSolver"
Element = "p:1 b:4"
Bubbles in Global System = False
Variable = FlowVar
Variable Dofs = 4
Convective = Logical False
Block Diagonal A = Logical True
Use Velocity Laplacian = Logical False
!Keywords related to the block preconditioning
Block Preconditioning = Logical True
Linear System Scaling = Logical True
Linear System Row Equilibration = Logical True
Linear System Solver = "Iterative"
Linear System GCR Restart = Integer 200
Linear System Max Iterations = 200
Linear System Convergence Tolerance = 1.0e-6
Nonlinear System Max Iterations = 100
Nonlinear System Convergence Tolerance = 1.0e-5
Nonlinear System Newton After Tolerance = 1.0e-3
```

End

- The outer iteration of the saddle-point problem
- Pre-defined GCR method
- Needs the 2 dummy-solver (uses memory)

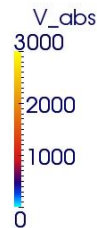
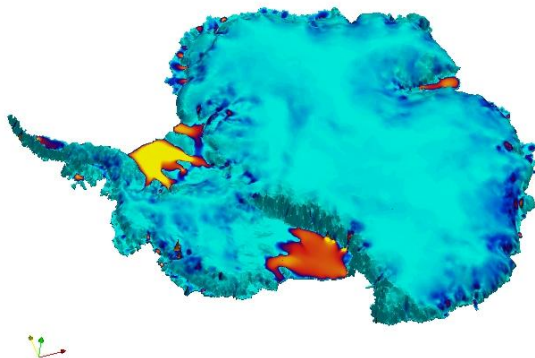
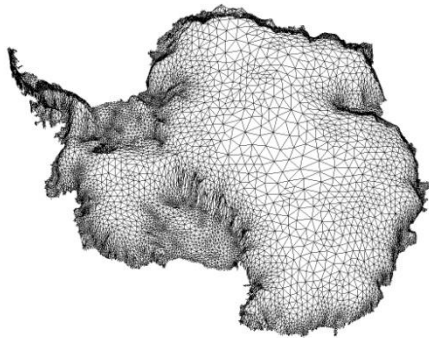
Mass consistent normals

- ➊ Especially on noisy bed with linear test functions normal vectors are discontinuous
 - Artificial sink/source of mass
- ➋ New way to deduce mass consistent nodal normal vectors from elements

$$\vec{n}_j = \frac{1/N_j \sum_{i=1}^{N_j} \int_{\Omega_k} \vec{n}(\vec{x}_j) \varphi_k dV}{\|1/N_j \sum_{i=1}^{N_j} \int_{\Omega_k} \vec{n}(\vec{x}_j) \varphi_k dV\|}$$

Mass consistent normals = Logical True

Results AAIS



- 2D footprint reordered by YAMS (60k elements)
- Internally extruded using ALBMAP dataset (NetCDF reader + StructMeshMapper)
- Temperatures interpolated from Pattyn-output
- Sliding values from inversion on coarser mesh
- Block-Preconditioner as solution

Results AAIS

