



# Elmer/Ice Grenoble 2017

## *Shallow models in Elmer/Ice*

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- **Shallow Shelf / Shallow stream Solver**
- **Thickness Solver**
- **Current / planned development**



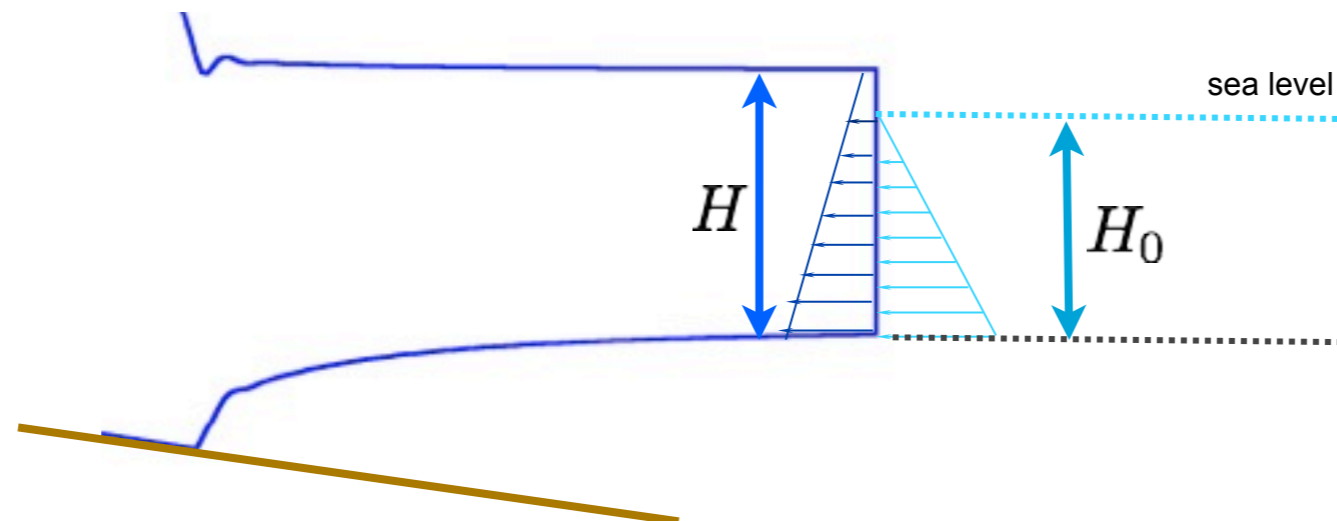
# Shallow Shelf Approximation/Shallow Stream Approximation

## Field equations:

$$\begin{cases} \frac{\partial}{\partial x} \left( 2H\nu \left( 2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \beta u = \rho g H \frac{\partial z_s}{\partial x} \\ \frac{\partial}{\partial x} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( 2H\nu \left( \frac{\partial u}{\partial x} + 2\frac{\partial v}{\partial y} \right) \right) - \beta v = \rho_i g H \frac{\partial z_s}{\partial y} \end{cases}$$

## Boundary Conditions:

$$\begin{cases} 4H\nu \frac{\partial u}{\partial x} n_x + 2H\nu \frac{\partial v}{\partial y} n_x + H\nu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} \right) n_y = (\rho_i g H - \rho_w g H_0) n_x \\ 4H\nu \frac{\partial v}{\partial y} n_y + 2H\nu \frac{\partial v}{\partial x} n_y + H\nu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} \right) n_x = (\rho_i g H - \rho_w g H_0) n_y \end{cases}$$



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$$H = Z_s - Z_b$$

## Elmer/Ice Solvers:

**Solver Fortran File:** SSASolver.f90

**Solver Name:** SSABasalSolver

**Required Output Variable(s):**

- SSAVelocity

**Required Input Variable(s):**

- (1) Zb, Zs and Effective Pressure when using the Coulomb type friction law

The SSABasalSolver solve the classical SSA equation, it has been modified in Rev. 6440 to be executed either on a grid of dimension lower than the problem dimension itself (i.e. the top or bottom grid of a 2D or 3D mesh for a SSA 1D or 2D problem), or on a grid of the same dimension of the problem (i.e. 2D mesh for a 2D plane view SSA solution).

**It will work on a 3D mesh only** if the mesh as been extruded along the vertical direction and if the base line boundary conditions have been preserved (to impose neumann conditions). **Keyword «Preserve Baseline = Logical True» in section Simulation**



# Shallow Shelf Approximation/Shallow Stream Approximation

## Field equations:

$$\begin{cases} \frac{\partial}{\partial x} \left( 2H\nu \left( 2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \beta u = \rho g H \frac{\partial z_s}{\partial x} \\ \frac{\partial}{\partial x} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( 2H\nu \left( \frac{\partial u}{\partial x} + 2\frac{\partial v}{\partial y} \right) \right) - \beta v = \rho_i g H \frac{\partial z_s}{\partial y} \end{cases}$$

## SIF - Solver Section:

```
Solver 1
Equation = "SSA"
Procedure = File "ElmerIceSolvers" "SSABasalSolver"
Variable = String "SSAVelocity"
Variable DOFs = 2 ! 1 in SSA 1-D or 2 in SSA-2D

Linear System Solver = Direct
Linear System Direct Method = umfpack

Nonlinear System Max Iterations = 100
Nonlinear System Convergence Tolerance = 1.0e-08
Nonlinear System Newton After Iterations = 5
Nonlinear System Newton After Tolerance = 1.0e-05

Nonlinear System Relaxation Factor = 1.00

Steady State Convergence Tolerance = Real 1.0e-3
End
```



# Shallow Shelf Approximation/Shallow Stream Approximation

## Field equations:

$$\begin{cases} \frac{\partial}{\partial x} \left( 2H\nu \left( 2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \beta u = \rho g H \frac{\partial z_s}{\partial x} \\ \frac{\partial}{\partial x} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( 2H\nu \left( \frac{\partial u}{\partial x} + 2\frac{\partial v}{\partial y} \right) \right) - \beta v = \rho g H \frac{\partial z_s}{\partial y} \end{cases}$$

## SIF - Material Section:

Material 1

### ! Flow Law

Viscosity Exponent = Real \$1.0/n  
 Critical Shear Rate = Real 1.0e-10  
 SSA Mean Viscosity = Real \$eta  
 SSA Mean Density = Real \$rhoi

### ! Friction Law

! Which law are we using  
 SSA Friction Law = String («linear», «weertman» or «coulomb»)

! friction parameter  
 SSA Friction Parameter = Real 0.1

### ! Needed for Weertman and Coulomb

! Exponent m  
 SSA Friction Exponent = Real \$1.0/n

! Min velocity for linearisation where ub=0  
 SSA Friction Linear Velocity = Real 0.0001

### ! Needed for Coulomb only

! post peak exponent in the Coulomb law (q, in Gagliardini et al., 2007)  
 SSA Friction Post-Peak = Real ...  
 ! Iken's bound tau\_b/N < C (see Gagliardini et al., 2007)  
 SSA Friction Maximum Value = Real ....  
 SSA Min Effective Pressure = Real ...

### Friction laws:

- Linear:

$$\tau_b = \beta u$$

- Weertman:

$$\tau_b = \beta |u|^{(m-1)} u$$

- Coulomb:

$$\tau_b = \frac{1}{A_s^{\frac{1}{n}}} \left[ \frac{1}{(1 + \alpha \cdot \chi^q)} \right]^{\frac{1}{n}} \cdot u_b^{\frac{1}{n} - 1} \cdot u$$

$$\alpha = \frac{(q-1)^{q-1}}{q^q} \quad \chi = \frac{u_b}{C^n N^n A_s}$$



# Shallow Shelf Approximation/Shallow Stream Approximation

## Field equations:

$$\begin{cases} \frac{\partial}{\partial x} \left( 2H\nu \left( 2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \beta u = \rho g H \frac{\partial z_s}{\partial x} \\ \frac{\partial}{\partial x} \left( H\nu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left( 2H\nu \left( \frac{\partial u}{\partial x} + 2\frac{\partial v}{\partial y} \right) \right) - \beta v = \rho_i g H \frac{\partial z_s}{\partial y} \end{cases}$$

## Boundary Conditions:

$$\begin{cases} 4H\nu \frac{\partial u}{\partial x} n_x + 2H\nu \frac{\partial v}{\partial y} n_x + H\nu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} \right) n_y = (\rho_i g H - \rho_w g H_0) n_x \\ 4H\nu \frac{\partial v}{\partial y} n_y + 2H\nu \frac{\partial v}{\partial x} n_y + H\nu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} \right) n_x = (\rho_i g H - \rho_w g H_0) n_y \end{cases}$$

## SIF - Boundary Conditions / Constants / Body Forces:

```
Boundary Condition 1
! Dirichlet condition
SSAVelocity 1 = Real ...
SSAVelocity 2 = Real ...
End
Boundary Condition 1
! Neumann Condition
Calving Front = Logical True
End
```

```
Constants
! Used for Neumann condition
Water Density = Real ....
Sea Level = Real ...
End
```

```
Body Force 1
! The gravity from Flow Body Force 2/3 (1D/2D)
Flow BodyForce 3 = Real $gravity
End
```



# Computing mean values

SSA uses mean viscosity and density:

$$\nu(x, y) = \frac{1}{H} \int_{z_b}^{z_s} \mu(x, y, z) dz \longrightarrow \text{coupling with : Temperature, Damage}$$

$$\bar{\rho}(x, y) = \frac{1}{H} \int_{z_b}^{z_s} \rho(x, y, z) dz \longrightarrow \text{coupling with : Porous solver}$$

You can use:

## Elmer/Ice solver : *GetMeanValueSolver*

- **unstructured** meshes in the vertical direction

```
Solver 1
Equation = "SSA-IntValue"
Procedure = File "ElmerIceSolvers" "GetMeanValueSolver"
Variable = -nooutput String "Integrated variable"
Variable DOFs = 1

Exported Variable 1 = String "Mean Viscosity"
Exported Variable 1 DOFs = 1
Exported Variable 2 = String "Mean Density"
Exported Variable 2 DOFs = 1

Linear System Solver = Direct
Linear System Direct Method = umfpack

Steady State Convergence Tolerance = Real 1.0e-3
End

!!! Upper free surface
Boundary Condition 1
Depth = Real 0.0
Mean Viscosity = Real 0.0
Mean Density = real 0.0
End
```

## Elmer solver : *StructuredProjectToPlane*

- **structured** meshes in the vertical direction

```
Solver 1
Equation = "HeightDepth"
Procedure = "StructuredProjectToPlane" "StructuredProjectToPlane"
Active Coordinate = Integer 3

Operator 1 = depth
Operator 2 = height
Operator 3 = thickness

!! compute the integrated horizontal Viscosity and Density
Variable 4 = Viscosity
Operator 4 = int

Variable 5 = Density
Operator 5 = int
End

Material 1
SSA Mean Viscosity = Variable "int Viscosity", thickness
REAL MATC "tx(0)/tx(1)"
SSA Mean Density = Variable "int Density", thickness
REAL MATC "tx(0)/tx(1)"
End
```

=> We are working on new solutions for this step and to compute the 3D velocity field  
(=> coupling with damage and temperature)





- Shallow Shelf / Shallow stream Solver
- **Thickness Solver**
- Current / planned development



# Thickness Solver

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## Field equations:

$$\frac{\partial H}{\partial v} + \nabla(\bar{u}H) = a_s + a_b$$

## Elmer/Ice Solvers:

- **Solver Fortran File:** ThicknessSolver.f90
- **Solver Name:** ThicknessSolver
- **Required Output Variable(s):** H
- **Required Input Variable(s):** H residual
- **Optional Output Variable(s):** dhdt
- **Optional Input Variable(s):** FlowSolution

- This solver is based on the FreeSurfaceSolver and use a **SUPG stabilisation** scheme by **default** (*residual free bubble stabilization* can be use instead).
- As for the FreeSurfaceSolver **Min and Max limiters** can be used.
- As for the Free surface solver **only a Dirichlet boundary condition** can be imposed.
- This solver can be used on a mesh of the same dimension as the problem (e.g. solve on the bottom or top boundary of a 3D mesh to solve the 2D thickness field) or on a mesh of lower dimension (e.g. can be use in a 2D plane view mesh with the SSA Solver solver for example)



# Thickness Solver

Field equations:  $\frac{\partial H}{\partial v} + \nabla(\bar{u}H) = a_s + a_b$

## SIF:

```
Solver 1
Equation = "Thickness"
Variable = -dofs 1 "H"

Exported Variable 1 = -dofs 1 "H Residual"

!! To compute dh/dt
Exported Variable 2 = -dofs 1 "dHdt"
Compute dHdT = Logical True

Procedure = "ElmerIceSolvers" "ThicknessSolver"
! Before Linsolve = "EliminateDirichlet" "EliminateDirichlet"

Linear System Solver = Direct
Linear System Direct Method = umfpack
Linear System Convergence Tolerance = Real 1.0e-12

! equation is linear if no min/max
Nonlinear System Max Iterations = 50
Nonlinear System Convergence Tolerance = 1.0e-6
Nonlinear System Relaxation Factor = 1.00

! stabilisation method: [stabilized\bubbles]
Stabilization Method = stabilized

!! to apply Min/Max limiters
Apply Dirichlet = Logical True

!! to use horizontal ALE formulation
ALE Formulation = Logical True

!! To get the mean horizontal velocity
!! either give the name of the variable
Flow Solution Name = String "SSAVelocity"
!!!! or give the dimension of the problem using:
! Convection Dimension = Integer
End
```

```
Body Force 1
!! Mass balance
Top Surface Accumulation = Real ....
Bottom Surface Accumulation = Real ....

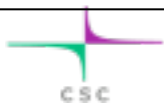
!! if the convection velocity is not directly given by a variable
!! Then give //Convection Dimension = Integer// in the solver section
!! and the Mean velocity here:
Convection Velocity 1 = Variable int Velocity 1, thickness
REAL MATC "tx(0)/tx(1)"
Convection Velocity 2 = Variable int Velocity 2, thickness
REAL MATC "tx(0)/tx(1)"

End
```

```
Boundary Condition 1
! Dirichlet condition only
H = Real ...
End
```

```
Material 1
!! Limiters
Min H = Real ....
Max H = Real ....

End
```



# Coupling SSA solver / Thickness solver - Method 1

SSASolver uses  $Z_s$  and  $Z_b$  ( $H=Z_s-Z_b$ )

=> requires an intermediate step between *ThicknessSolver* and *SSASolver*

*Do it yourself:*

```
Initial Condition 1
  H = Real ....
End

Body Force 1
! to update Zb and Zs according to H evolution
  Zb = Real ...
  Zs = Variable Zb , H
      REAL MATC "tx(0)+tx(1)"
End

Solver 1
Equation = "UpdateExport"
Procedure = "ElmerIceSolvers" "UpdateExport"
Variable = -nooutput "dummy"

Exported Variable 1 = -dofs 1 "Zb"
Exported Variable 2 = -dofs 1 "Zs"
End

Solver 2
Equation = "SSA"
Procedure = File "ElmerIceSolvers" "SSABasalSolver"
Variable = String "SSAVelocity"
Variable DOFs = 2 ! 1 in SSA 1-D
End

Solver 3
Equation = "Thickness"
Variable = -dofs 1 "H"
End
```

you can write a User Function to apply flotation to  $Z_b$  and  $Z_s=Z_b+H$

1. From  $H$  compute  $Z_b$  and  $Z_s$   
look for definition of Exported variables in «Body Force»

2. From  $Z_b$  and  $Z_s$  compute  $u$

3. From  $u$  compute  $H$



# Coupling SSA solver / Thickness solver with Flotation solver

Flotation Solver in Elmer/Ice since 13 Nov. 2017 (commit b213b0c8c0639e12c4ab497f1ef7553a356209a4)

```
Initial Condition 1
  H = Real ....
  bedrock = ....
End

Constants
  Sea level = Real ... ! zsea
  Water Density = Real ... !rho_w
End

Material 1
  SSA Mean Density = Real ...
End

Solver 1
  Equation = "Flotation"
  Procedure = "ElmerIceSolvers" "Flotation"
  Variable = "GroundedMask"

  Exported Variable 1 = -dofs 1 "Zs"
  Exported Variable 2 = -dofs 1 "Zb"
  Exported Variable 3 = -dofs 1 "bedrock"
End

Solver 2
  Equation = "SSA"
  Procedure = File "ElmerIceSolvers" "SSABasalSolver"
  Variable = String "SSAVelocity"
  Variable DOFs = 2 ! 1 in SSA 1-D
End

Solver 3
  Equation = "Thickness"
  Variable = -dofs 1 "H"
End
```

1. From H compute Zb and Zs  
using flotation criterion

$$z_b = z_{sea} - H \frac{\rho_i}{\rho_w}$$

$$z_b = \max(z_b, bedrock)$$

2. From Zb and Zs compute u

3. From u compute H



# Check volume and fluxes using SaveScalars

```
Solver X  
Exec Solver = After Timestep  
  
Equation = "Save Scalars"  
Procedure = File "SaveData" "SaveScalars"  
  
Filename = File "Scalars_"$name$.dat"  
  
Variable 1 = "Time"  
  
! int H = Volume  
Variable 2 = "H"  
Operator 2 = "int"  
  
! int dh/dt = dVolume/dt  
Variable 3 = "dhdt"  
Operator 3 = "int"  
  
! int SMB  
Variable 4 = "smb"  
Operator 4 = "int"  
  
! SMB_H=Artificial additional Mass flux due to limits on H  
Variable 5 = "h residual"  
Operator 5 = "sum"  
  
! OUT Flow  
Variable 6 = "SSAVelocity"  
Operator 6 = "convective flux"  
Coefficient 6 = "Flux"  
  
! => Dvolume/dt ~ SMB + SMB_H - OUT  
End
```

Not with bubbles stabilisation

```
Material 1  
!! For Save scalar to compute mass flux (=H*SSA_UV)  
Flux = Equals H  
End  
  
Boundary Condition 1  
Target Boundaries = 1  
  
Save Scalars = Logical True  
  
Calving Front = Logical True  
  
End
```



# Examples

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## Friction Laws:

ismip diagnostic test cases

`[ELMER_TRUNK]/elmerice/Tests/SSA_Coulomb`

`[ELMER_TRUNK]/elmerice/Tests/SSA_Weertman`

## Coupling SSA/Thickness:

`[ELMER_TRUNK]/elmerice/Tests/SSA_IceSheet`

`[ELMER_TRUNK]/elmerice/examples/Test_SSA`



ismip prognostic test:

- 1D (2D mesh)
- 2D (2D mesh)
- 2D (3D mesh; use *StructuredProjectToPlane* to compute mean values))

## Coupling Stokes/Thickness:

ismip prognostic test:

`[ELMER_TRUNK]/elmerice/Tests/ThicknessSolver`

## Coupling Stokes/SSA:

MISMIP test:

`[ELMER_TRUNK]/elmerice/Tests/MISMIP_FS-SSA`



# Current/planned developments

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## Inverse methods:

- AdjointSolver for SSA => constrain friction, mean viscosity,  $Z_b$ ,  $Z_s$  from observation
  - *Fürst et al.*, Assimilation of Antarctic velocity observations provides evidence for uncharted pinning points, *The Cryosphere*, 2015
  - *Fürst et al.*, Passive shelf ice: the safety band of Antarctic ice shelves, *Nature Climate Change*, accepted
- AdjointSolver for Thickness => constrain  $u$ ,  $smb$  from observations of  $H$   
(see Morlighem *et al.*, 2011, a mass conservation approach for mapping glacier ice thickness)

## SSA\*:

- modify viscosity to take into account vertical shearing  
(see Cornford *et al.*, 2013, adaptive mesh, finite volume modeling of marine ice sheets)

## Sub-Element parameterisation at GL:

- sub-element parameterisation of friction in the GL vicinity (test flotation at IPs; increased number of IPS in firns floating elements; see Seroussi *et al.* (2014))

## Efficient hybrid model SSA+SIA

## Efficient coupling with Temperature and Damage

## Anisotropic mesh adaptation

