

Elmer/Ice advanced workshop 2017

Grenoble, France



CSC – Finnish research, education, culture and public administration ICT knowledge center

Calving Models in Elmer/Ice

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Continuum damage models (CDM)



Continuum damage model

- Existing CDM in Elmer/Ice
 - Krug, J., J. Weiss, O. Gagliardini and G. Durand, 2014. ***Combining damage and fracture mechanics to model calving***, *The Cryosphere*, **8**, 2101-2117, doi:[10.5194/tc-8-2101-2014](https://doi.org/10.5194/tc-8-2101-2014).
- Description of damage userfunction:
<http://elmerice.elmerfem.org/wiki/doku.php?id=userfunctions:damage>
- Main difficulty (to my understanding) is damage transport
- Changing rheology with respect to damage parameter

Calving using in-situ stress-based criteria (Joe Todd's stuff)



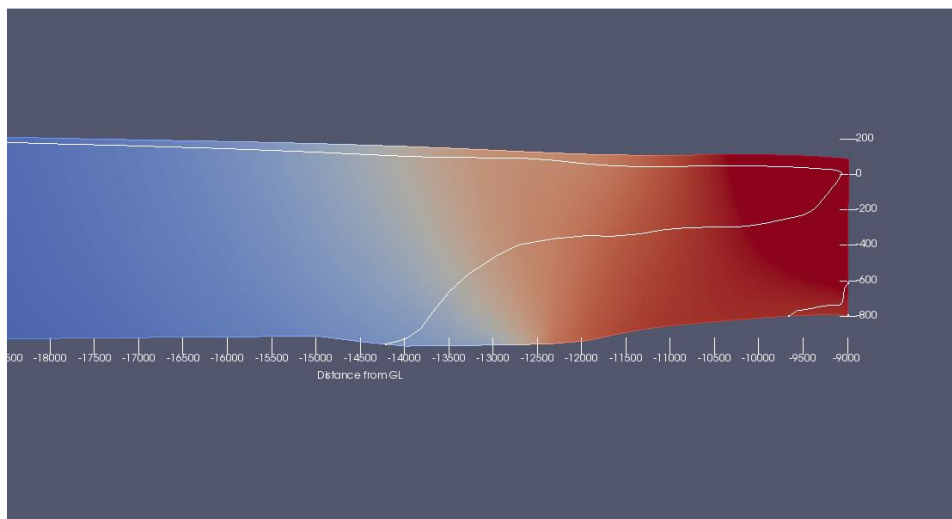
Calving using maximum extensional stress

- Code contributed by **Joe Todd** (Scott Polar/St. Andrews)
- Uses 3D Nye criterion to determine place of failure
 - Determining the max. principal stress, σ_3 , using [ComputeEigenValues](#)
 - Checking for places with $\sigma_3 > \sigma_{thresh.} \sim 0$
 - In-situ calving criterion (in opposite to CDM + transport)
- The “beef” is the calving/remeshing implementation

Elmer/Ice Calving Models

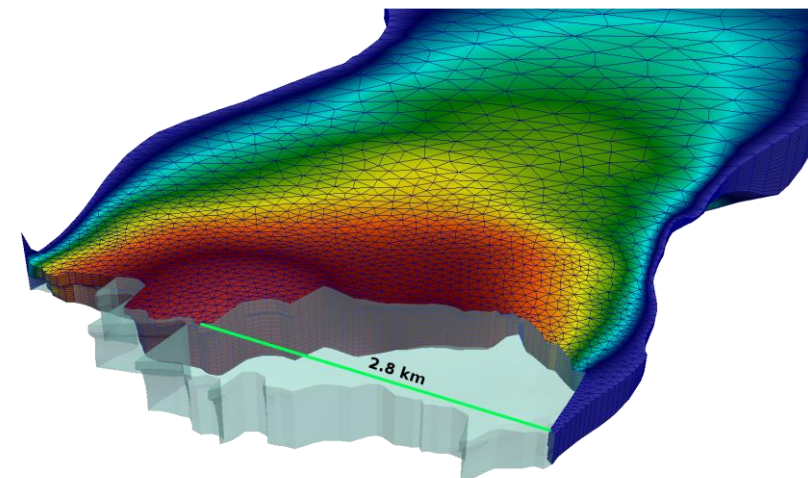
2D Calving:

- Calving = point on line
- Manipulate original mesh (accordion)
- Simple, fast, serial



3D Calving:

- Calving = line on surface
- Complete remeshing
- Complex, expensive, parallel
- Better



Elmer/Ice Calving Solvers

2D Calving:

- Calving.F90
- TwoMeshes.F90

2,000 lines of code

**Both use the
'crevasse depth
calving criterion' but
others could be
implemented easily.**

3D Calving:

- Calving3D.F90
- CalvingRemesh.F90
- ProjectCalving.F90
- CalvingGeometry.F90
- ComputeCalvingNormal.F90
- CalvingFrontAdvance3D.F90

11,000 lines of code

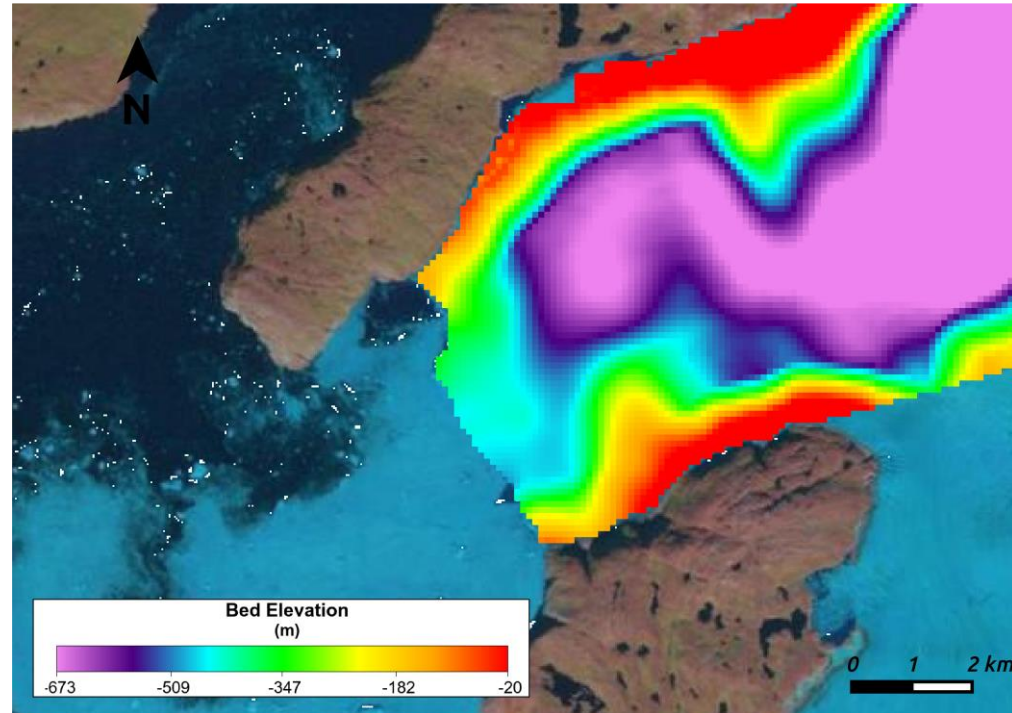
Dependencies

- Software:

- GMSH for remeshing
- NETCDF for GridDataReader
- Linux?

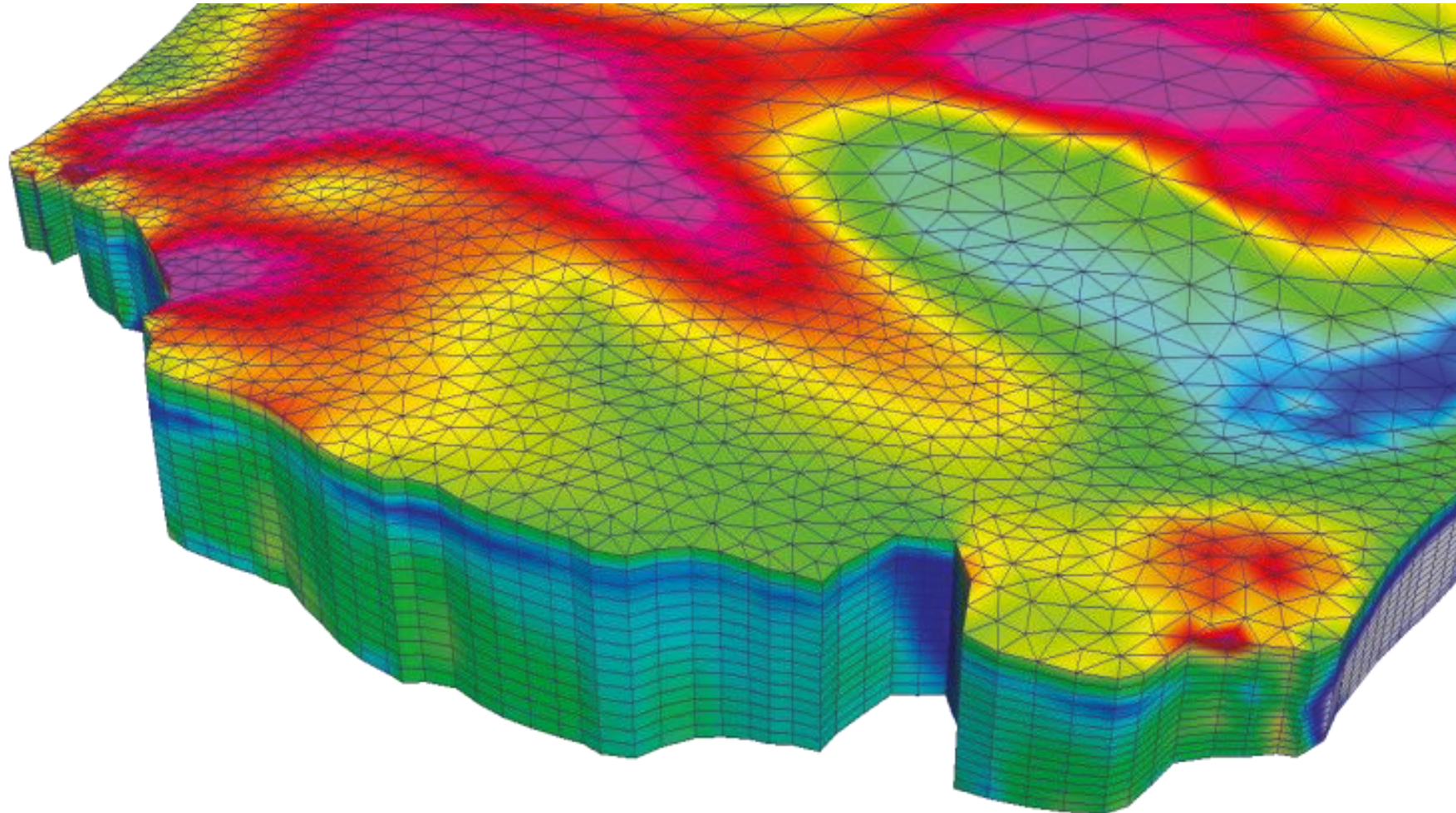
- Data:

- Accurate bed topography
- Initial terminus position
- Velocity for inversions

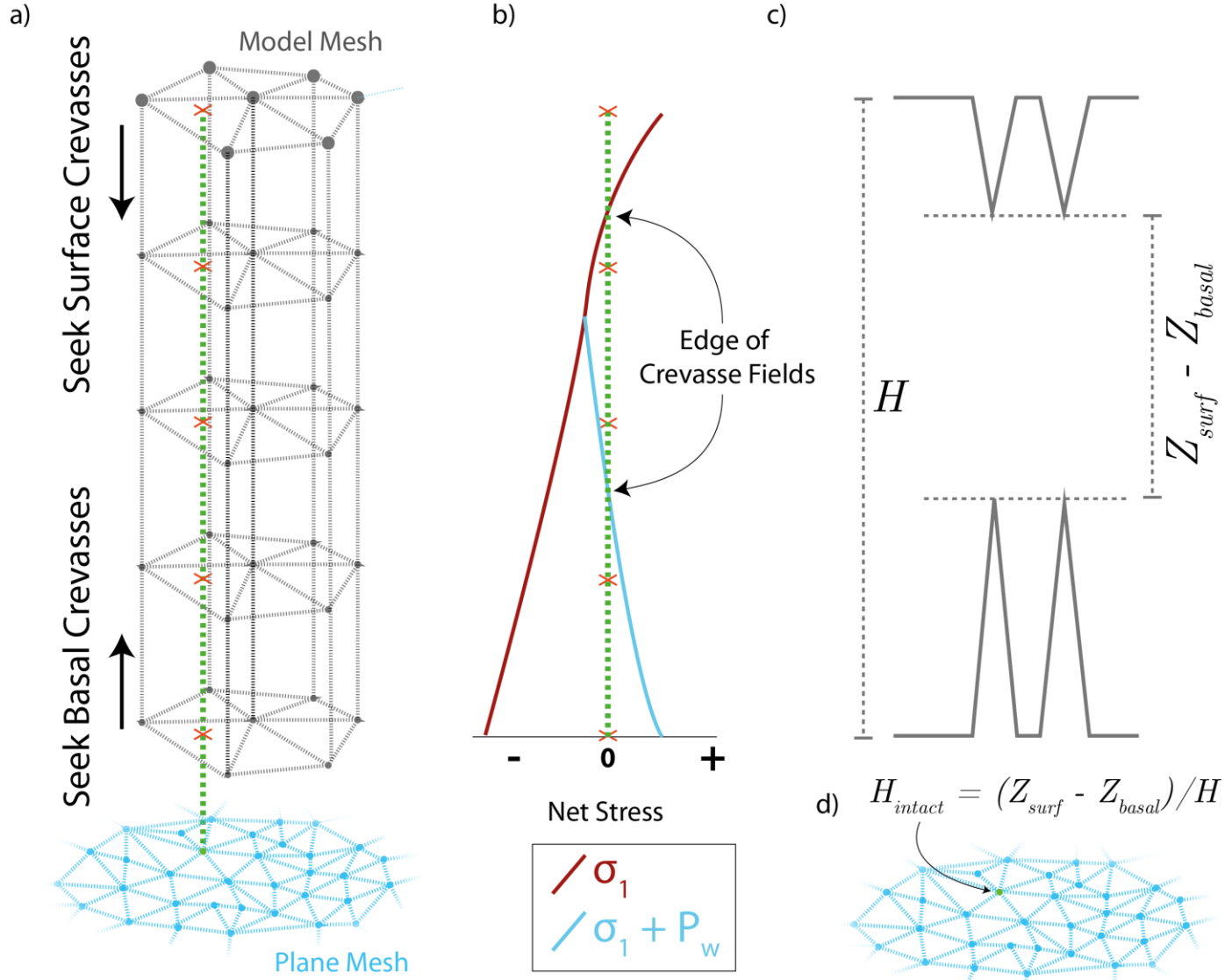


Basal topography produced via mass conservation.

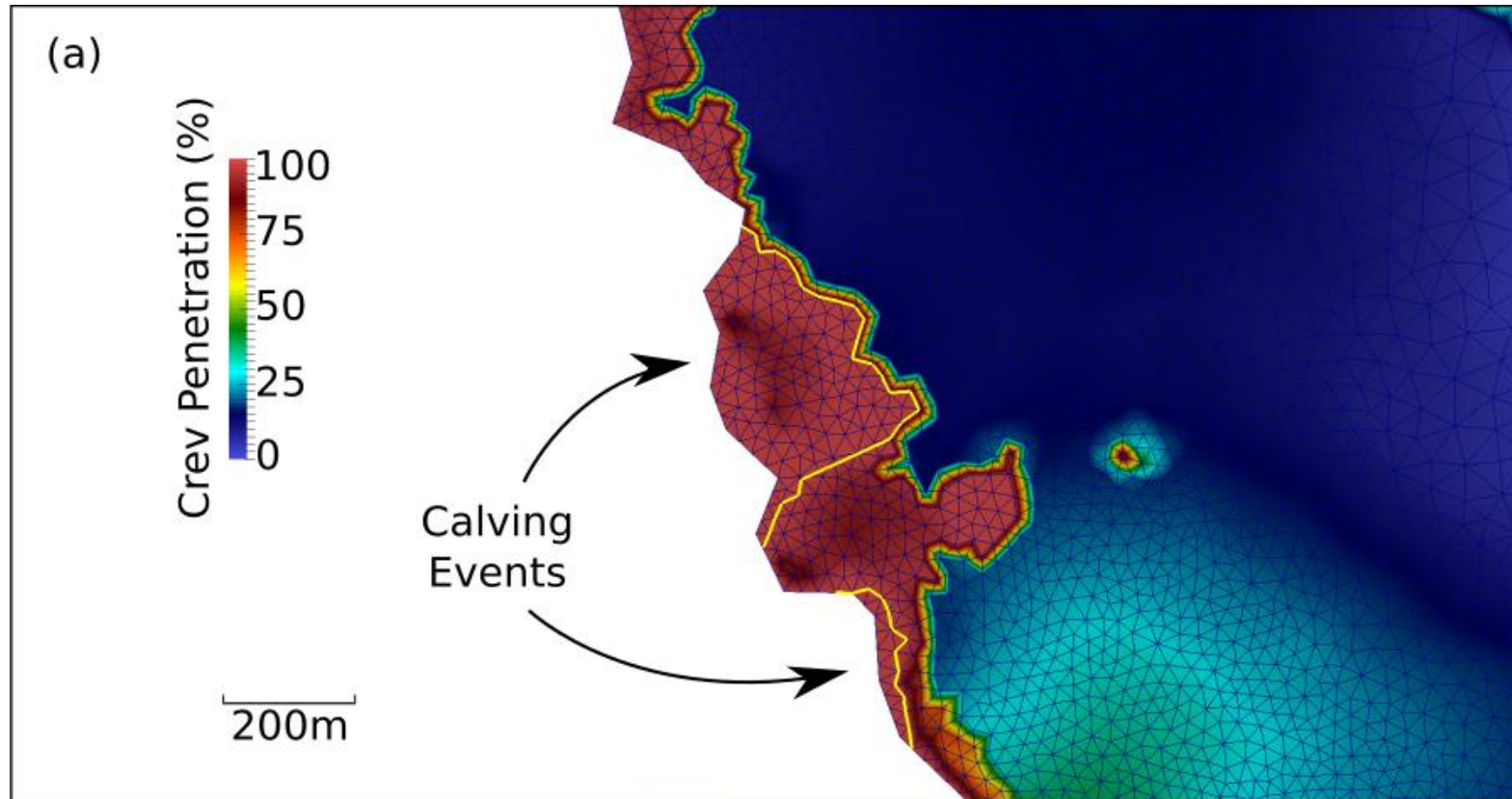
Predicting Calving



Predicting Calving



Predicting Calving



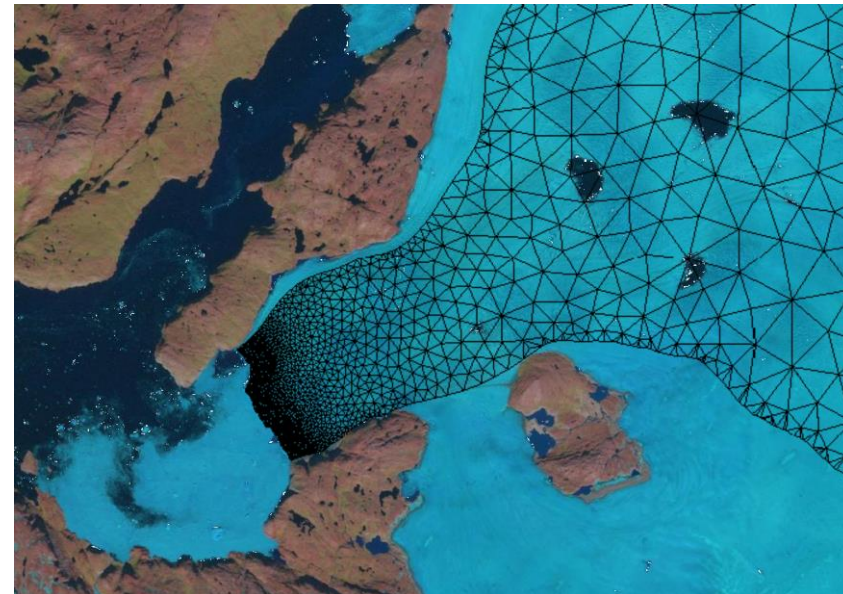
Remeshing

Input: Calving vector defined on front

Output: Good quality mesh with post-calving geometry & all field variables.

Method:

1. Produces 'post-calving' footprint
2. Mesh it in GMSH
3. Extrude it
4. Deform it
5. Interpolate variables

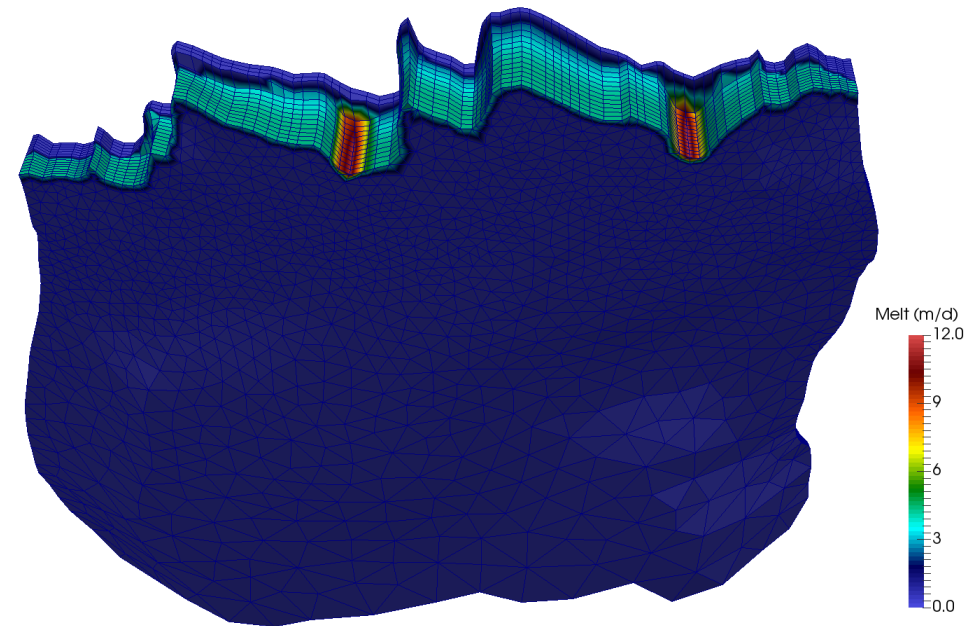


Terminus Advance

Continuous process, unlike calving
FreeSurfaceSolver doesn't work
CalvingFrontAdvance.F90 computes:

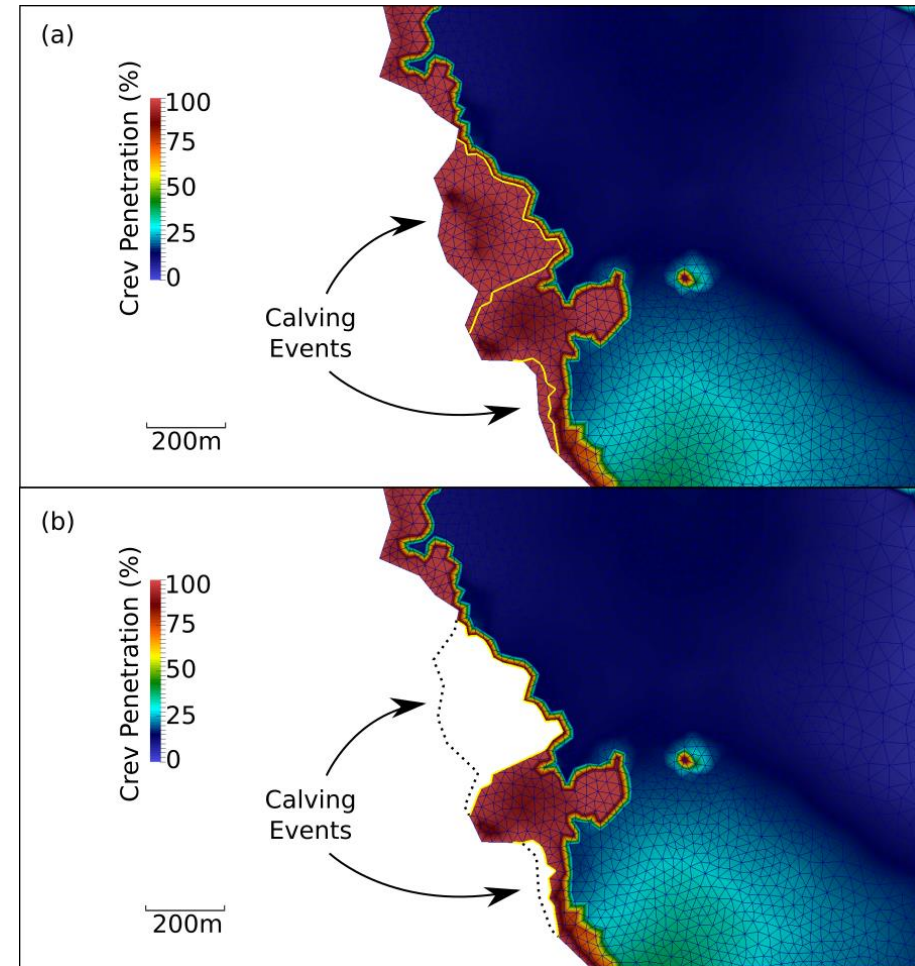
$$\vec{d} = (\vec{u} - a_{\perp} \vec{n}) dt$$

So nodes are free to move in any direction.



Adaptive Timestepping

- **Problem:** Calving events trigger 'follow-up' events, but timestepping introduces artificial delay.
- **Solution:** If a large calving event occurs, change the timestep size to quasi-steady state (1 day => 1 second) and recompute velocity, stress, calving.



Robustness & Stability

- Unsupervised remeshing causes issues
- “Check NS” looks for *suspicious* velocity solution and remeshes/rewinds
- Looks for:
 1. Convergence failure
 2. Very high velocity
 3. Large *changes* in velocity

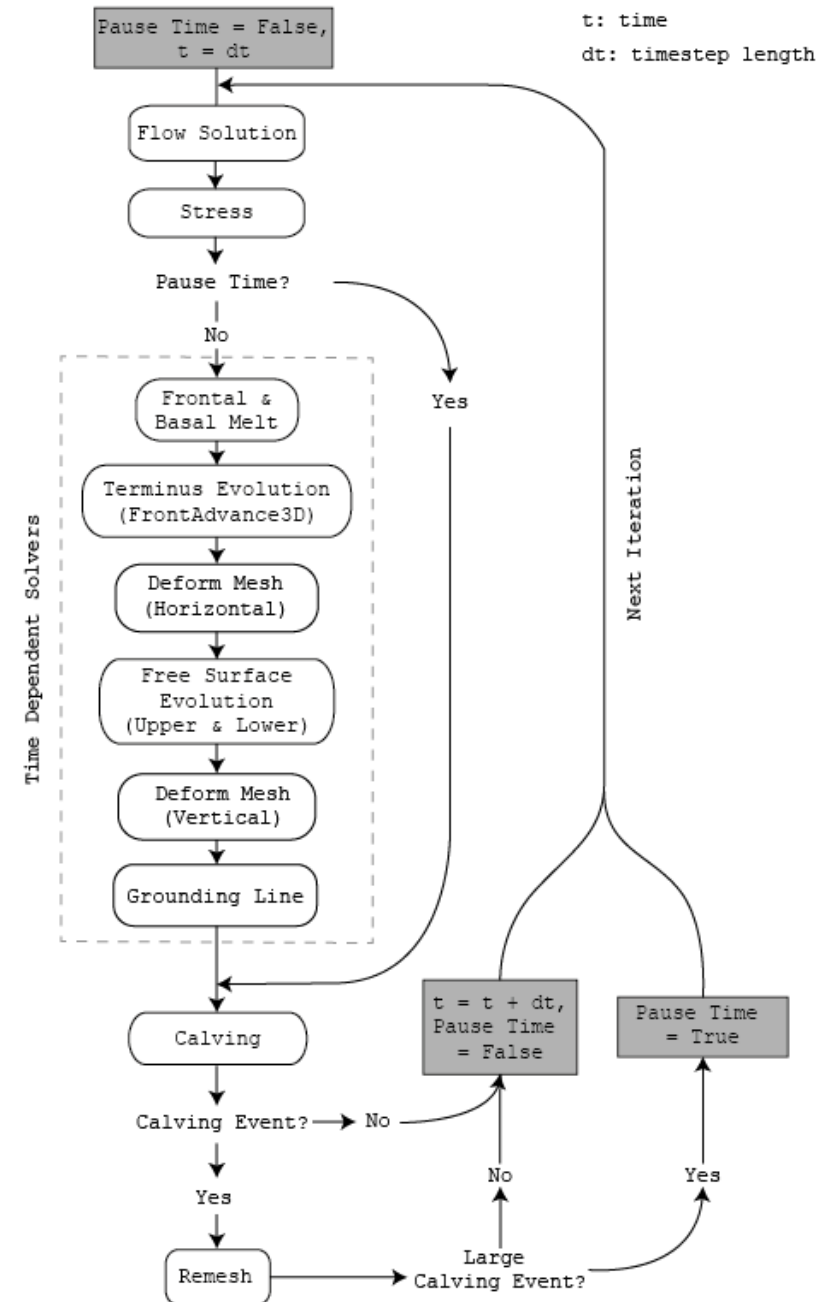
```
Solver 5
Equation = String "Check NS"
Procedure = File "ElmerIceSolvers" "CheckFlowConvergence"

Flow Solver Name = String "Flow Solution"
Maximum Flow Solution Divergence = Real 1.3
Maximum Velocity Magnitude = Real 1.0E6
First Time Max Expected Velocity = Real 8.0E4

!list of solvers to skip this time if NS fails to converge
Switch Off Equation 1 = String "StressSolver"
Switch Off Equation 2 = String "3D Calving"
Switch Off Equation 3 = String "Free Surface Top"
Switch Off Equation 4 = String "Free Surface Bottom"
Switch Off Equation 5 = String "Front Advance"
Switch Off Equation 6 = String "Longitudinal Mesh Update"
Switch Off Equation 7 = String "Vertical Mesh Update"
End
```


Typical Simulation

- Compute velocity & stress (and check!)
- Advance front
- Evolve upper & lower surfaces
- Look for calving
- Remesh, interpolate & continue



Getting Help

- Look at the **test cases** in: `elmerice/Tests/Calving*`
- Look at the **Elmer/Ice wiki** → Problems -> Calving
- Read the **source code!**

```
tElement % nodeindexes) .GT. 0))) CYCLE  
BC elements, stupid way of doing it, but whatever  
) nodeindexes == GoToNode))) CYCLE
```

- **Get in touch** – StAndrewsGlaciology.org

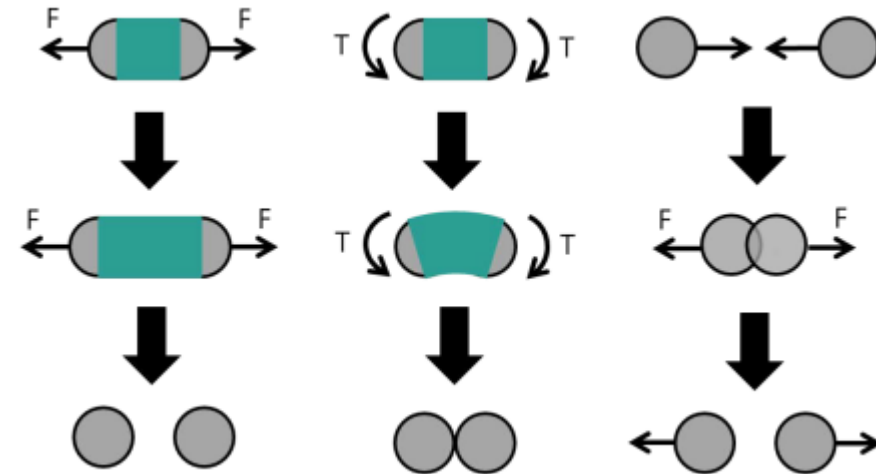


Coupling between Elmer/Ice and external model (Dorotheè Vallot, Jan Åström)



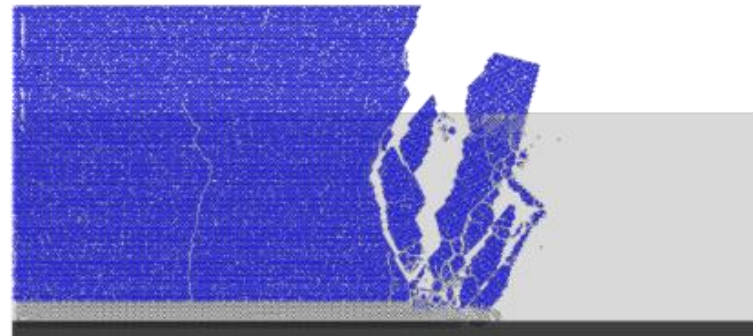
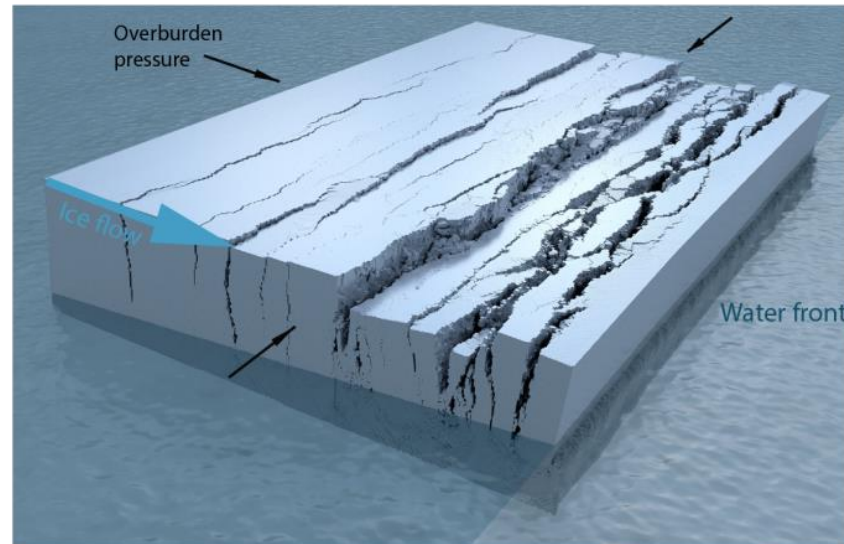
Discrete element model

- Numerical particle-based model (Åström et al., 2013) in 2D or 3D
- Glacier divided into discrete particles
- Frozen contacts
 - Beams
 - Inelastic interactions (dissipation of energy)
 - Breaking when elastic load > fracture threshold (stability tune)
- Sliding at the base



Discrete element model

- Is able to use first-principle approach on brittle failure of ice
- Can even include a viscous reaction
- Spatial-scales: resolves glacier in blocks of about $\Delta x = 10\text{m}$ length
- Timescales: $\frac{\Delta x}{c} \sim \frac{10}{5000} \sim 10\text{ms}$
- Severe constraints in applicability



Coupled discrete element – continuum model

- Used in a view instances already via offline-coupling, to either evaluate calving behaviour:

Åström, J.A., D. Vallot, M. Schäfer, E.Z. Welty, S. O’Neel, T.C. Bartholomaus, Yan Liu, T.I. Riikilä, T. Zwinger, J. Timonen, and J.C. Moore, 2014. *Termini of calving glaciers as self-organized critical systems*, Nature Geoscience, **7**, 874-878, doi:[10.1038/ngeo2290](https://doi.org/10.1038/ngeo2290)

Benn, D.I., J. Åström, T. Zwinger, J. Todd, F.M. Nick, S. Cook, N.R.J. Hulton, and A. Luckman, 2017. *Melt-under-cutting and buoyancy-driven calving from tidewater glaciers: new insights from discrete element and continuum model simulations*, Journal of Glaciology, 1-12, doi:[10.1017/jog.2017.41](https://doi.org/10.1017/jog.2017.41).

- Or to determine crevasse positions:

Y. Gong, T. Zwinger, J. Åström, B. Altena, T. Schellenberger, R. Gladstone, and J. C. Moore
Simulating the roles of crevasse routing of surface water and basal friction on the surge evolution of Basin 3, Austfonna, submitted to TC

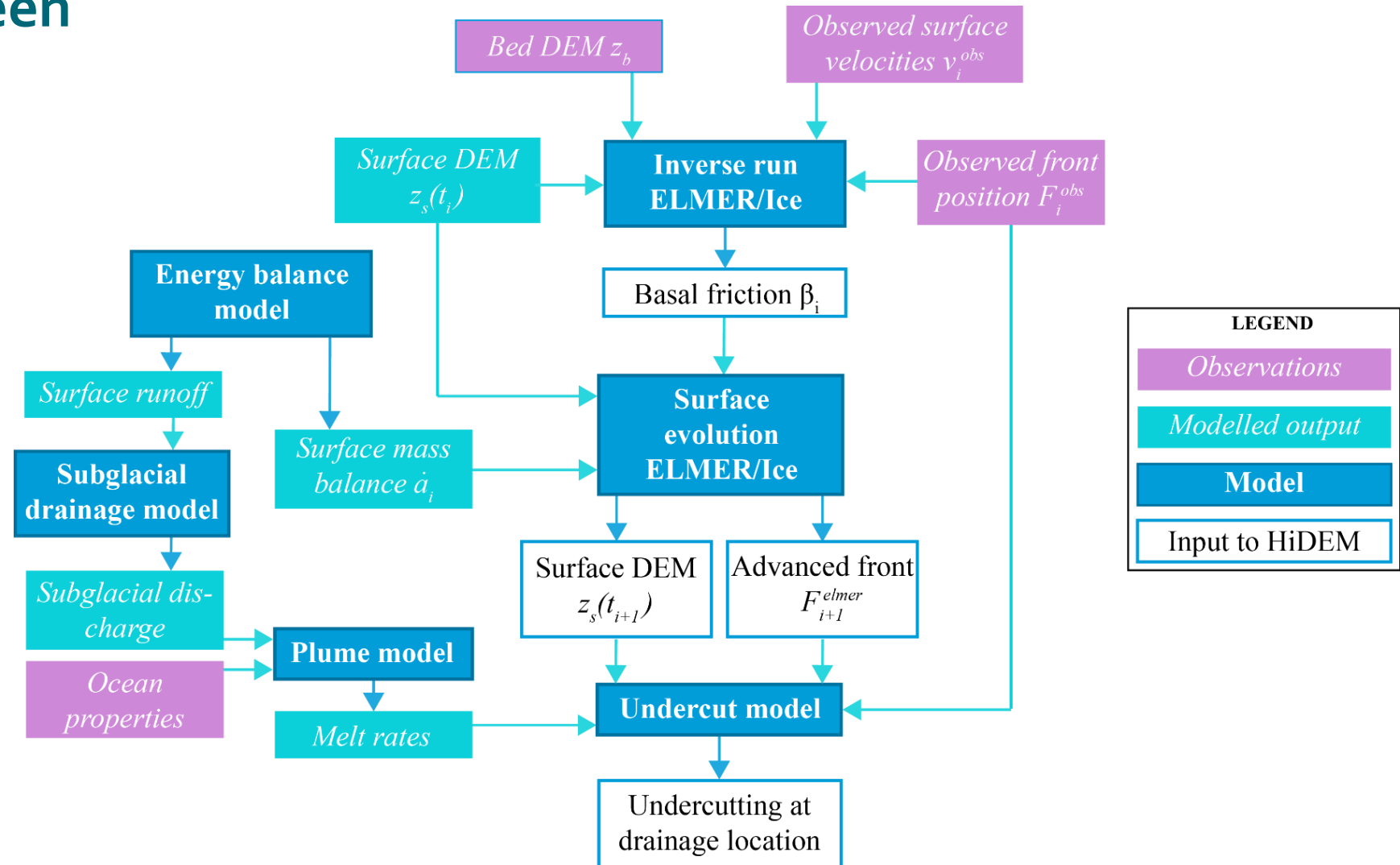
Test case: Kronebreen

- Tidewater glacier, one of the fastest in Svalbard archipelago
- Sliding at the base
- Started retreating in 2011
- Surface velocity and front positions available for 2014-2015
- High resolution surface and bed topography

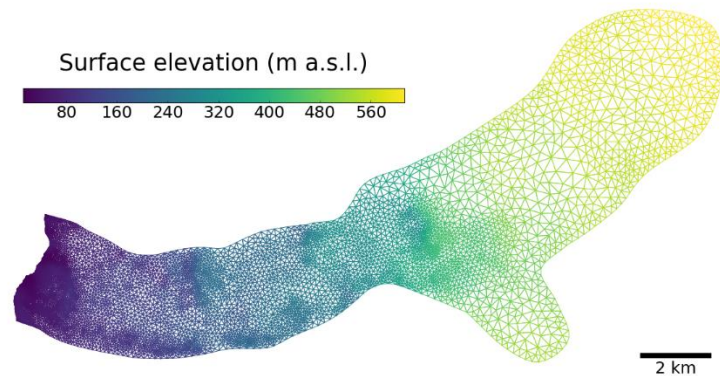


Test case: Kronebreen

- Work started by Dorothée Vallot
- Created workflow between Elmer/Ice, surface runoff, subglacial drainage, basal hydrology, plume model and undercutting
- Currently 2 submitted paper (see next slides)

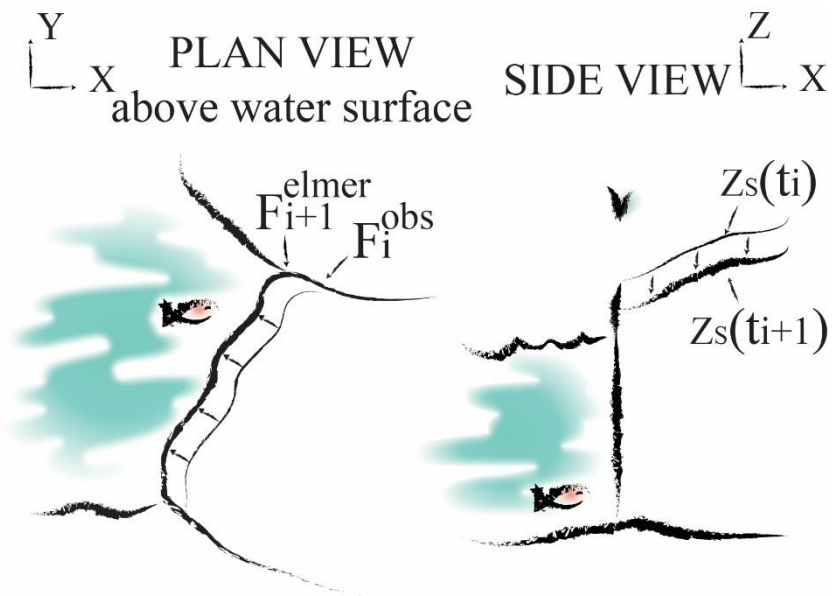


Step 1: Generate the mesh



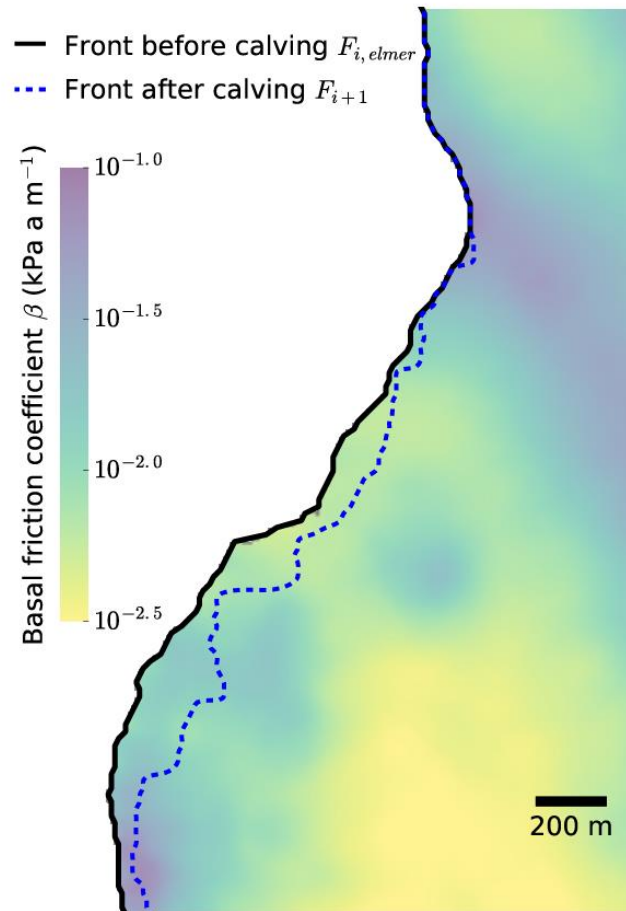
- From front position (initial or modelled) and contour
- Gmsh to create the mesh
- Conversion to Elmer format

Step 2-3: Transient advance with Elmer/Ice and conversion



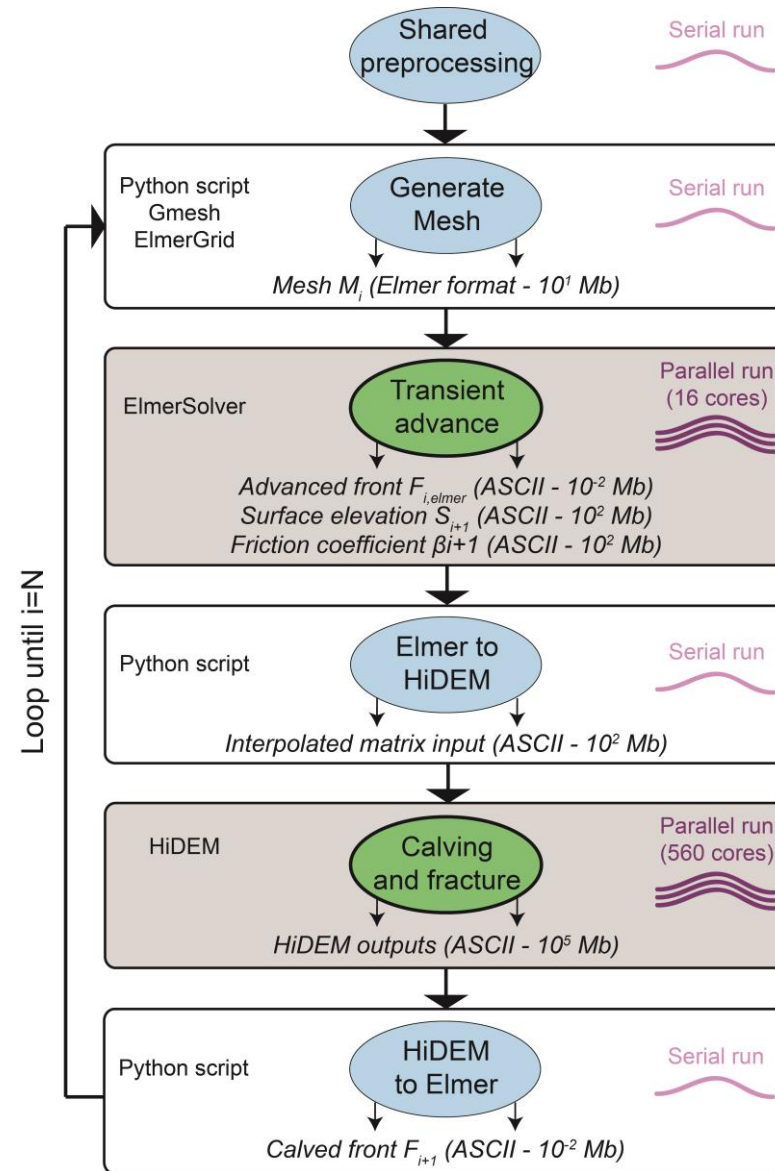
- Stokes equation
- Sliding law
- Surface and front evolution
- Long time period
- Conversion From Elmer/Ice to HiDEM domain

Step 4-5: Calving with HiDEM and new front position

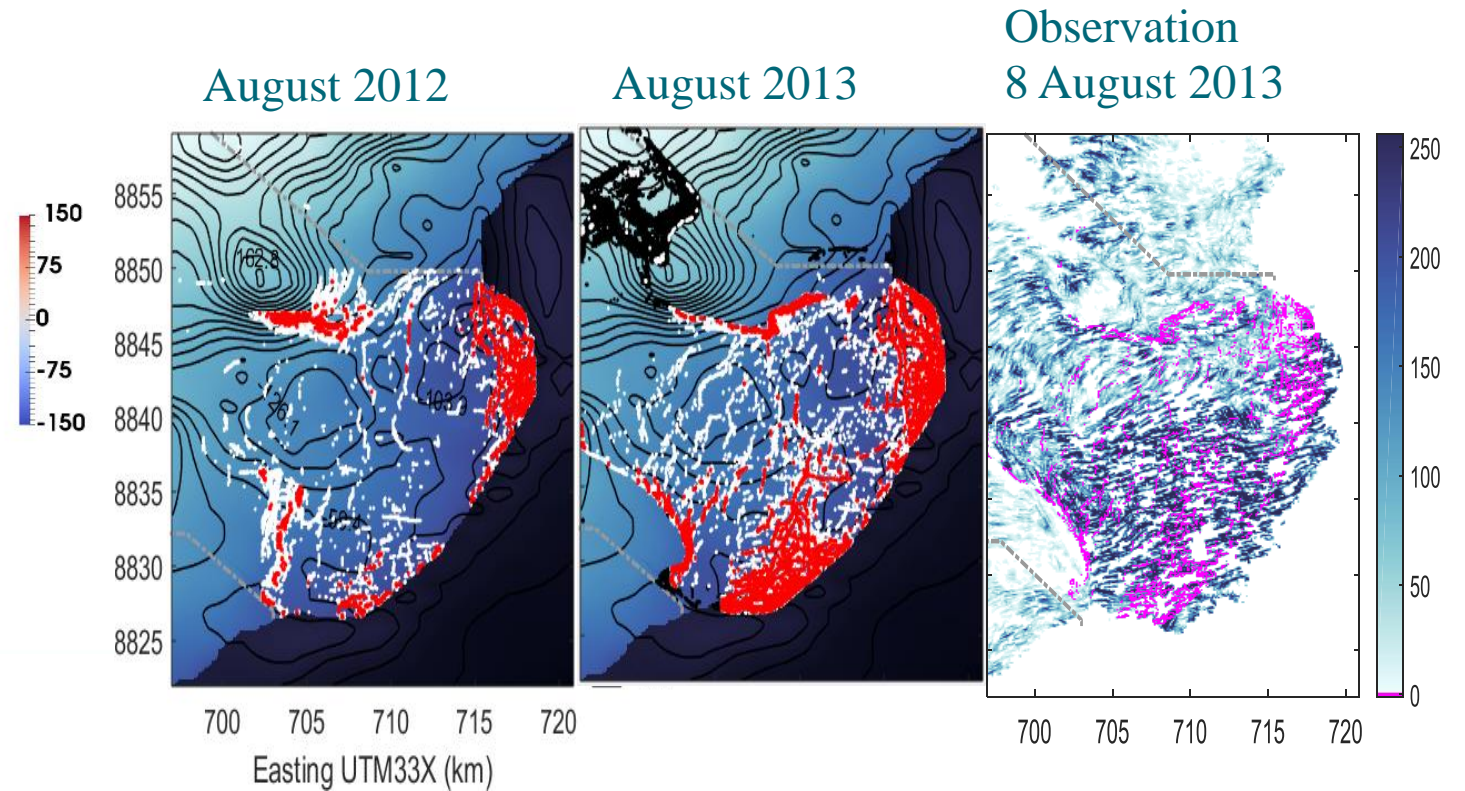
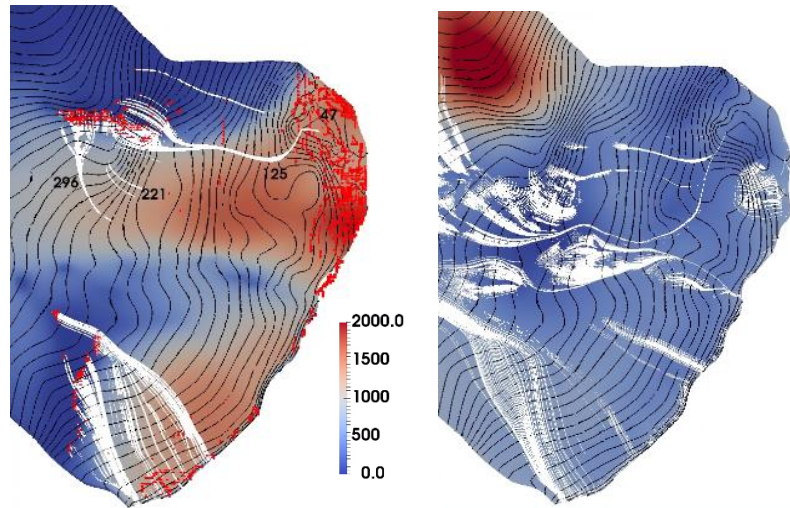


- Scaling of sliding to accommodate small time step (10^{-4} s)
- New front position to apply to the next step (meshing)

Summary



Crevasse patterns over Basin 3, Austfonna



Submitted manuscript by
Yongmei Gong, Thomas Zwinger, Jan Åström, Bas Altena, Thomas Schellenberger,
Rupert Gladstone, John C. Moore

Outlook

- Currently, a workflow using UNICORE to couple HiDEM and Elmer/Ice is being tested (eSTICC/NEiC activity) By Dorothee Vallot (Univ. Uppsala) and Shahbaz Memnon (Univ. Iceland)
- For usage of HiDEM, contact Jan Åström (givenname.familyname@csc.fi)
- Hard to estimate, if/when the model will be publicly available

