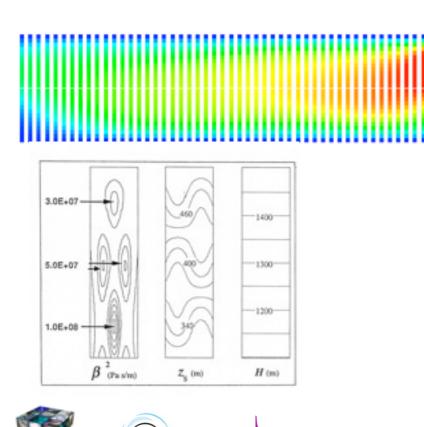




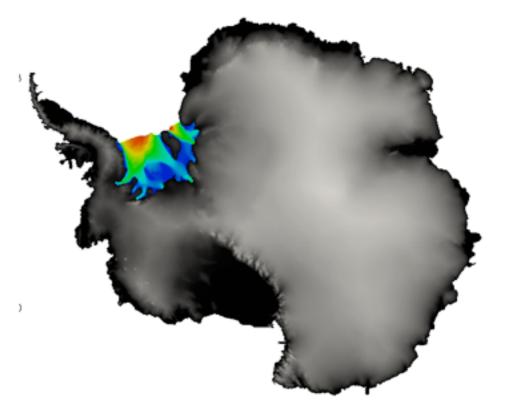
Inverse methods in Elmer/Ice Applications with the SSA



GE

Fabien Gillet-Chaulet

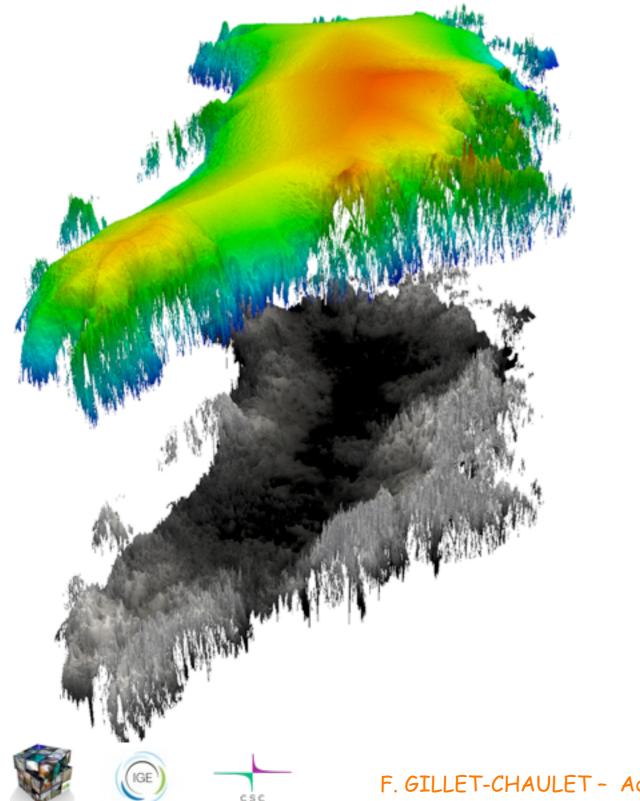
IGE - Grenoble - France

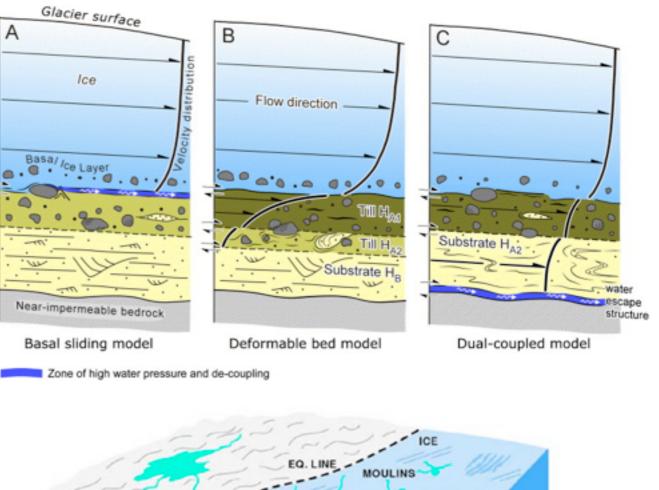


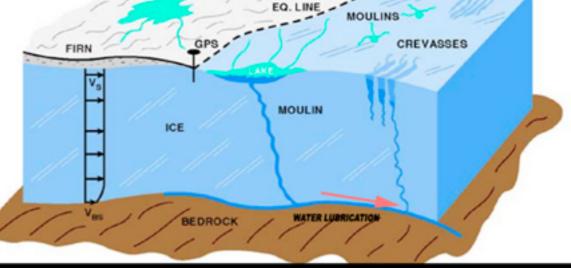


Uncertain parameterisations

e.g. friction of the ice on the bedrock highly variable in space and time Usually prescribed as a friction law Tau=f(u)

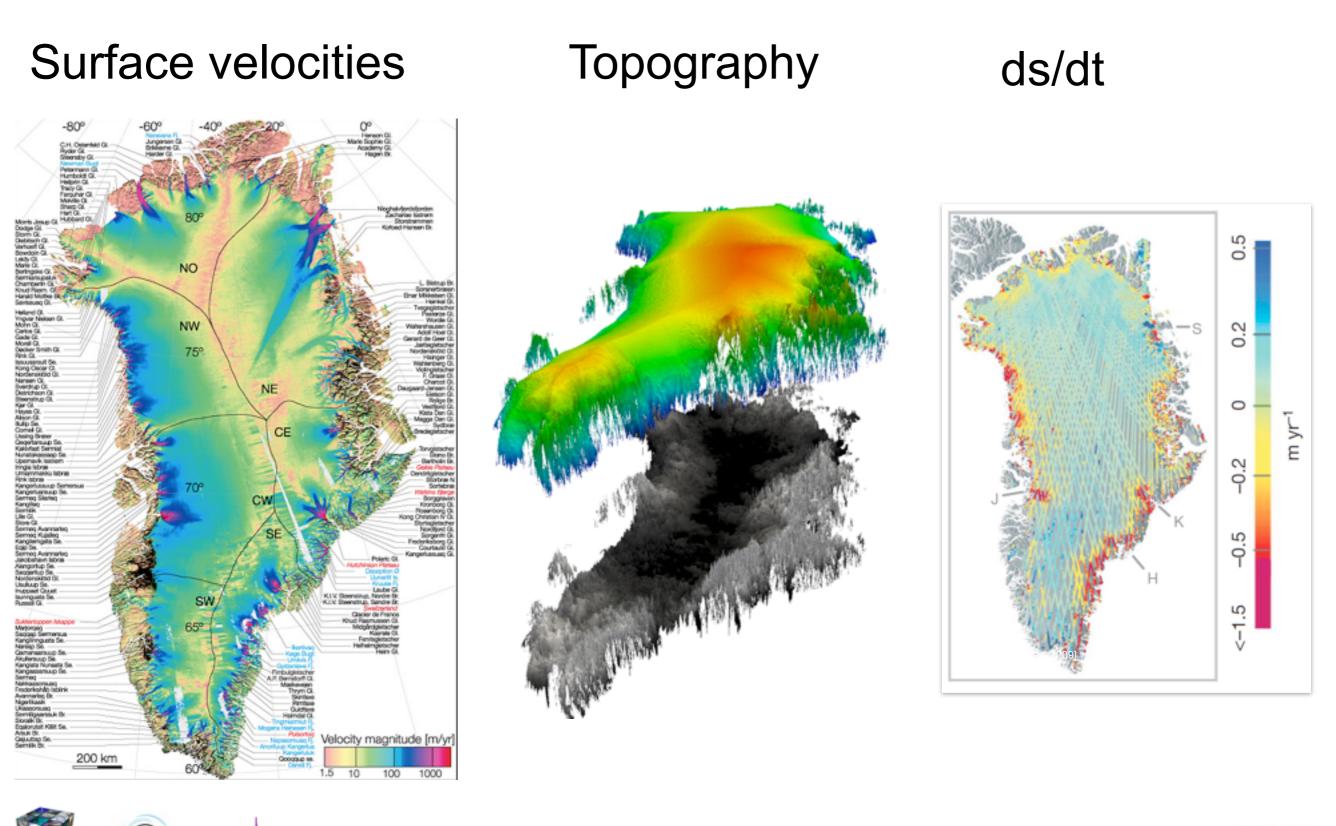






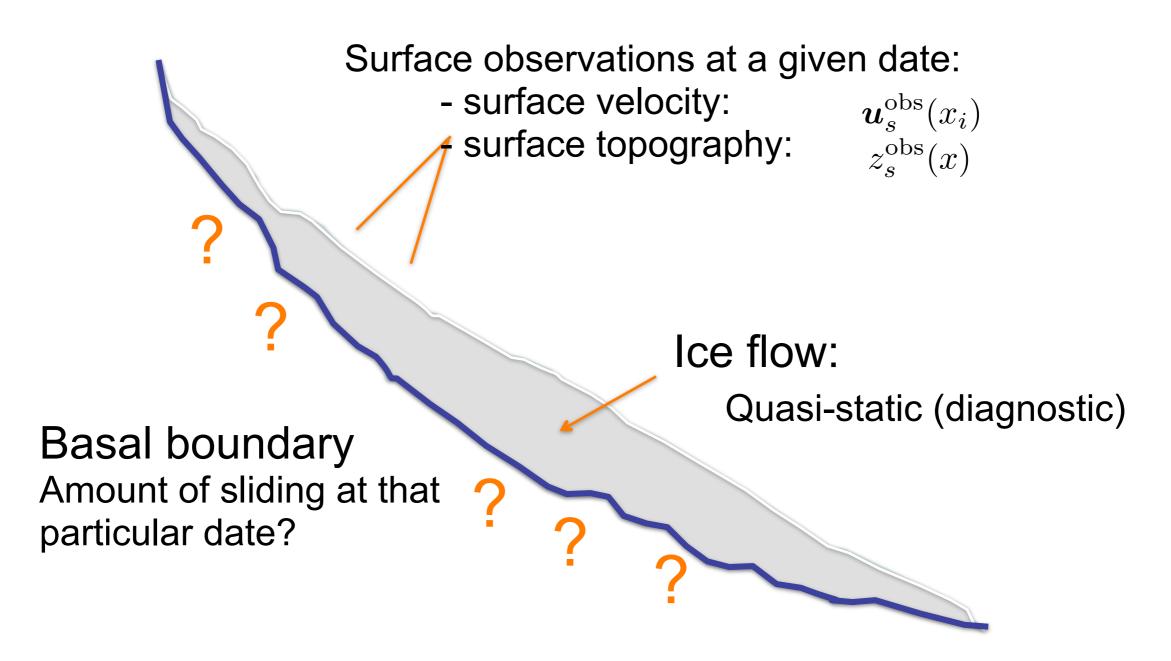
GLACIOLOGICAL FEATURES OF A MOULIN

CSC





Very low Reynolds -> no history in the velocity



Reconstruction of the basal conditions from surface measurements



Inverse methods in Elmer: balance equations

- STOKES: 2 inverse methods implemented in Elmer/Ice:
 - Robin inverse method (arthern and Gudmundsson, 2010)
 - Adjoint method (Mac Ayeal, 1993; Morlighem et al., 2010; Petra et al., 2012)

Characteristics:

=> restricted to **diagnostic** (no time evolution)

- => slip coefficient (Linear sliding law)
- => ice viscosity

=> could also do Neumann and Dirichlet BC (Adjoint method)

• SSA:

- Adjoint Method: in elmerice branch since 2016
- Not yet documented on the wiki
- Test case presented at the beginner course in Oslo in 2016
- Efficient minimisation library (quasi-Newton algorithm)





See pioneer paper from Mac Ayeal!!

Journal of Glaciology, Vol. 39, No. 131, 1993

A tutorial on the use of control methods in ice-sheet modeling

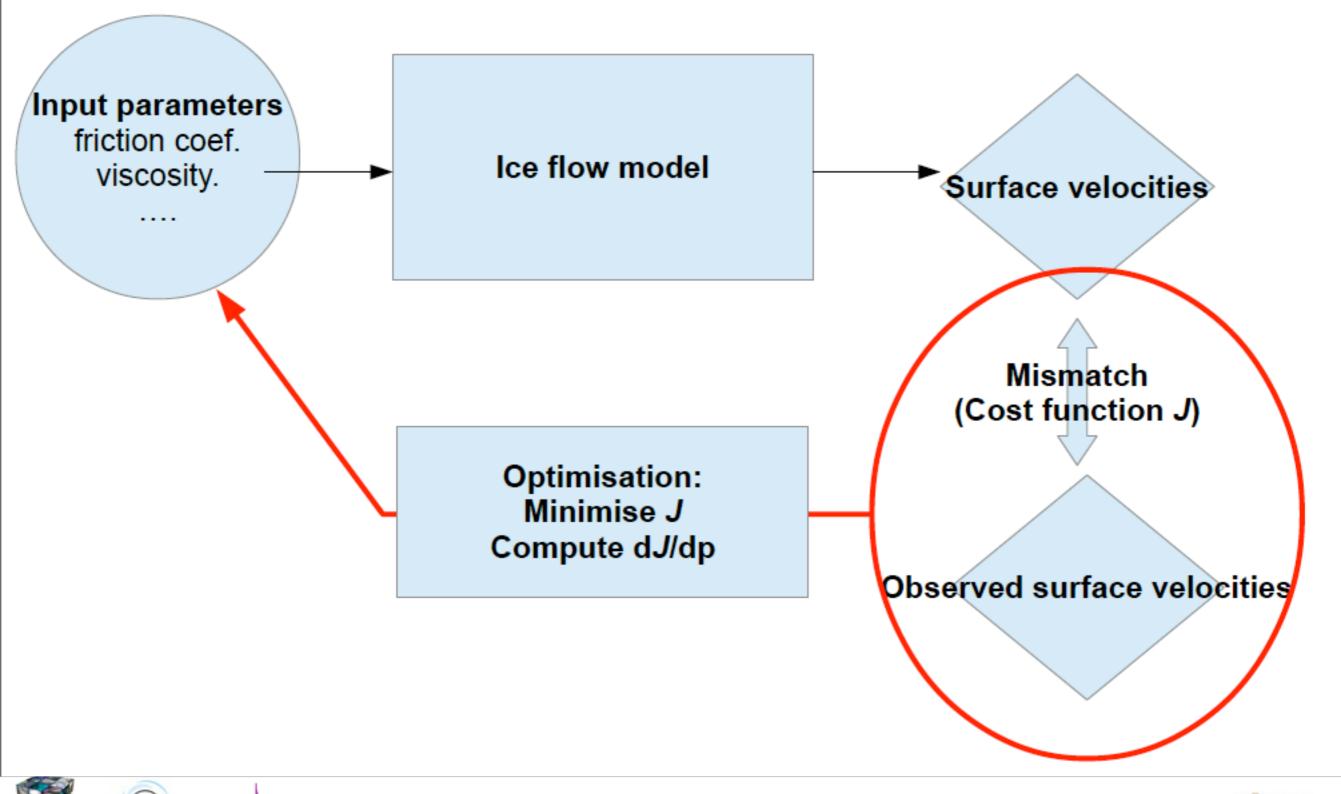
DOUGLAS R. MACAYEAL Department of the Geophysical Sciences, The University of Chicago, Chicago, Illinois 60637, U.S.A.





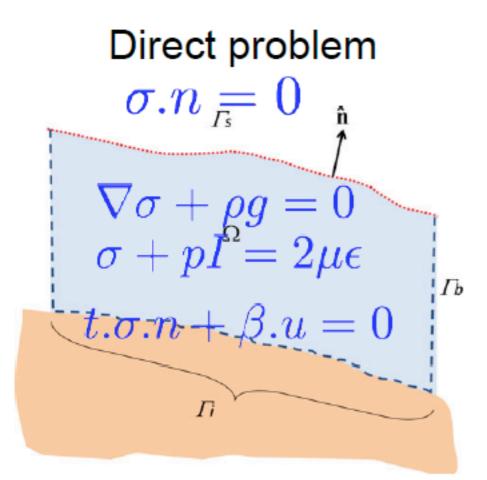


IGE









1. Define a cost function
$$J = f(u)$$

 $e.g. \quad J = \int_{\Gamma_S} \frac{1}{2} (u - u^{obs})^2 d\Gamma$

2. Insure that *u* is solution of your problem

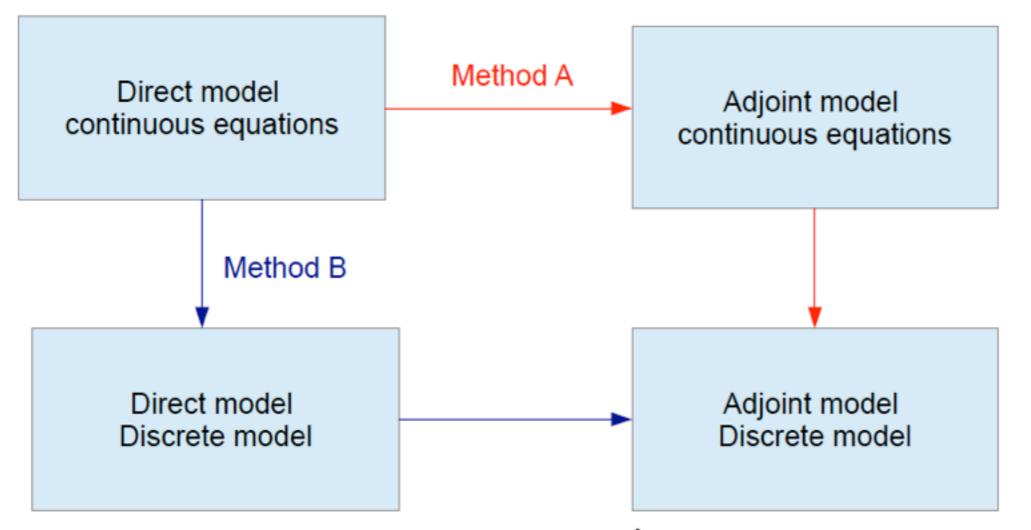
$$J' = J(u) + \Lambda(\nabla \sigma + \rho g)$$

3. Minimisation of J' requires that all variations are 0 $d_\Lambda J'=0 \Rightarrow$ direct problem equation is satisfied $d_u J'=0 \Rightarrow$ adjoint equations

=> gradient of *J* w.r. To input parameters *p*

$$d_p J = f(\Lambda, u)$$





Usually Method A ≠ Method B

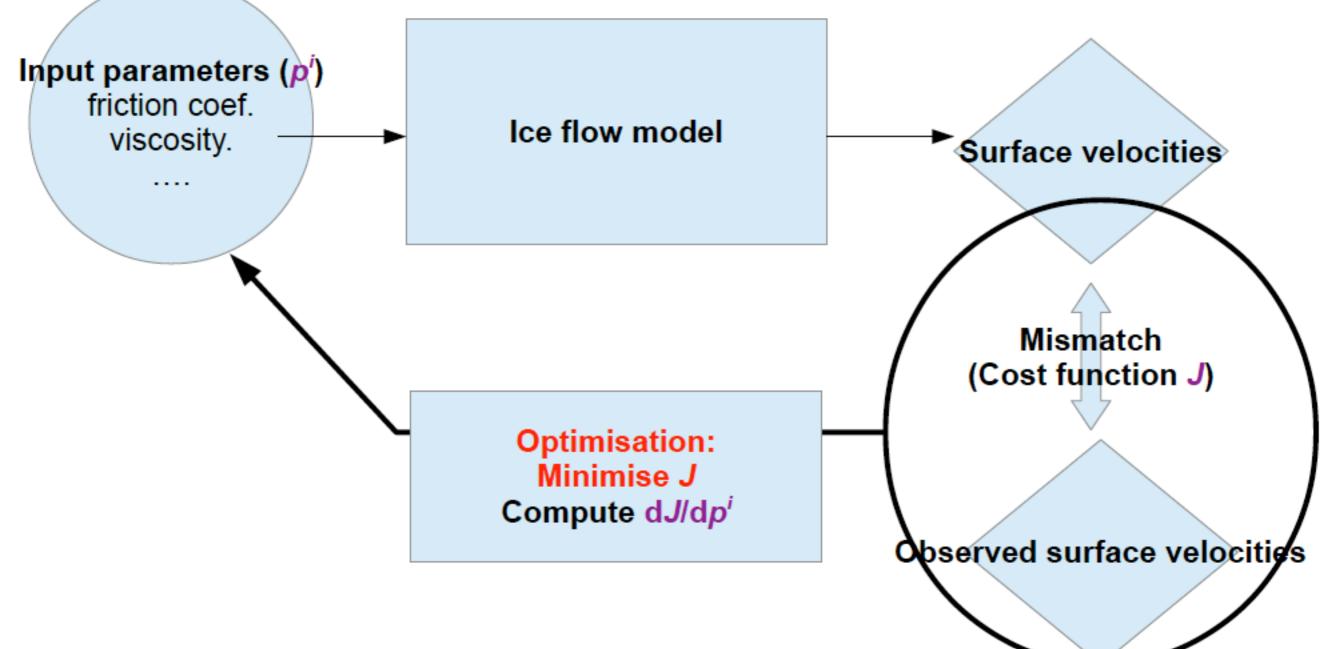
Method B should be preferred Can be done using automatic differentiation



Pointer arrays not yet supported

=> crucial parts have been derived by hand

Optimisation algorithm: M1QN3



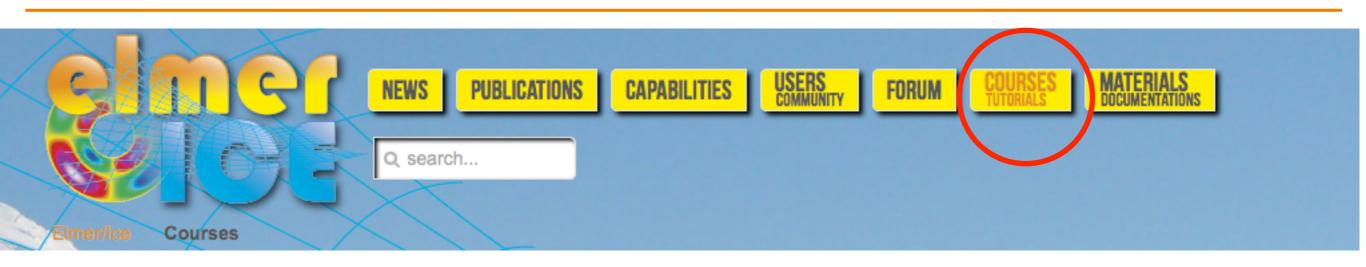
Optimisation done using the library M1QN3:

- Limited memory quasi-newton algorithm
- Implemented in reverse communication (i.e. called by Elmer within a solver)
- Iterative procedure: Input: pⁱ, Jⁱ, dJ/dpⁱ Output pⁱ⁺¹
- https://who.rocq.inria.fr/Jean-Charles.Gilbert/modulopt/optimization-routines/m1qn3/m1qn3.html





Stokes: Nothing new since the CSC - 2013 Advanced Course



CSC - Espoo - 4-6 November 2013

A 3-day Elmer/Ice advanced workshop was organised at CSC (Espoo, Finland) from the 4th to the 6th of November 2013. The course was held by Fabien Gillet-Chaulet (LGGE), Mika Malinen (CSC), Peter Råback (CSC) and Thomas Zwinger (CSC).

Title	Presentation	Material	
Introduction to Elmer	pdf	-	
Elmer Glaciological Modelling	pdf	f –	
Simple Hydro Toymodel	pdf	🚾 tar file	
Structured Meshes	mpdf	🚾 tar file	
Enhanced pre-processing	pdf	USB stick	
Block pre-conditioner	mpdf	USB stick	
Enhanced post-processing	pdf	ZIP archive	
Make-file for YAMS on Ubuntu 64bit	-	tar archive	
Mesh Adaptation using YAMS (see also these notes)	mpdf	tar archive	
Inverse methods	pdf	🙃 tar archive	

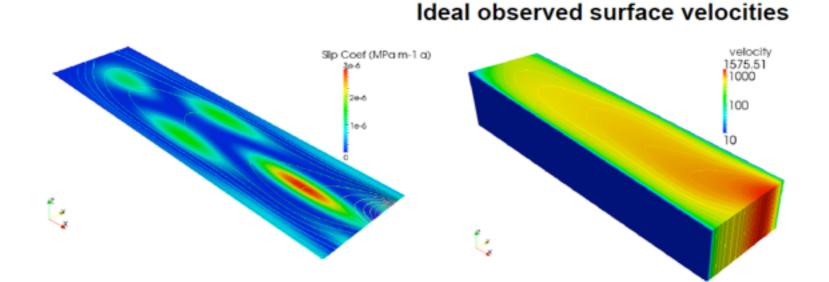




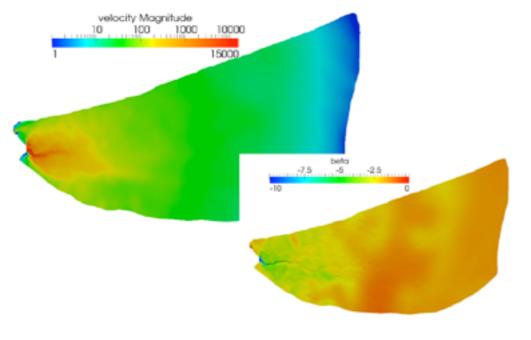


See the CSC-2013-Advanced Course Material:

 step by step construction of a «twin experiment» (set-up based on Mac Ayeal, 1993)



Application to Jacobshavn Isbrae drainage basin





Geosci. Model Dev., 6, 1299–1318, 2013 www.geosci-model-dev.net/6/1299/2013/ doi:10.5194/gmd-6-1299-2013 © Author(s) 2013. CC Attribution 3.0 License.





Capabilities and performance of Elmer/Ice, a new-generation ice sheet model

O. Gagliardini^{1,2}, T. Zwinger³, F. Gillet-Chaulet¹, G. Durand¹, L. Favier¹, B. de Fleurian¹, R. Greve⁴, M. Malinen³, C. Martín⁵, P. Råback³, J. Ruokolainen³, M. Sacchettini¹, M. Schäfer⁶, H. Seddik⁴, and J. Thies⁷
¹Laboratoire de Glaciologie et Géophysique de l'Environnement, UJF-Grenoble, CNRS – UMR5183, Saint-Martin-d'Hères, France
²Institut Universitaire de France, Paris, France
³CSC-IT Center for Science Ltd., Espoo, Finland
⁴Institute of Low Temperature Science, Hokkaido University, Sapporo, Japan
⁵British Antarctic Survey, Cambridge, UK
⁶Arctic Centre, University of Lapland, Rovaniemi, Finland
⁷Uppsala University, Uppsala, Sweden





Field equations:

$$\begin{cases} \frac{\partial}{\partial x} \left(2H\nu \left(2\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(H\nu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \beta u = \rho g H \frac{\partial z_s}{\partial x} \\ \frac{\partial}{\partial x} \left(H\nu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + \frac{\partial}{\partial y} \left(2H\nu \left(\frac{\partial u}{\partial x} + 2\frac{\partial v}{\partial y} \right) \right) - \beta v = \rho_i g H \frac{\partial z_s}{\partial y} \end{cases}$$

See applications:

• Assimilation of viscosity and friction:

- Fürst et al., Assimilation of Antarctic velocity observations provides evidence for uncharted pinning points, The Cryosphere, 2015
- Fürst et al., Passive shelf ice: the safety band of Antarctic ice-shelves, Nature Climate Change, 2016

• Assimilation of bedrock topography and friction:

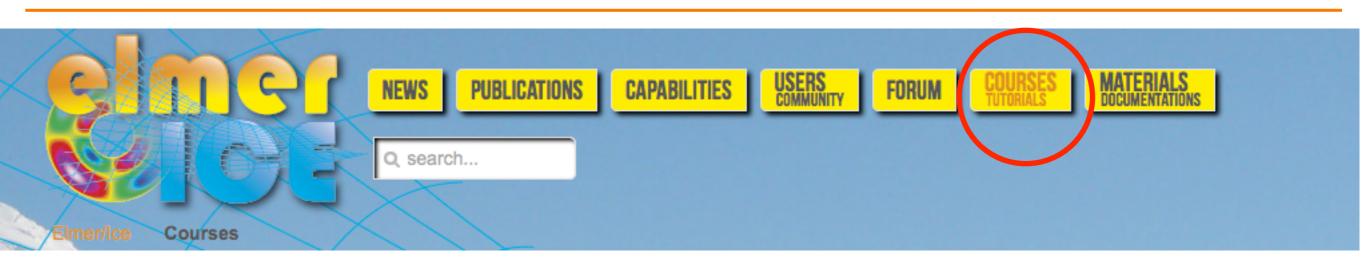
• Mosbeux, C., Gillet-Chaulet, F., Gagliardini, O., 2016. Comparison of adjoint and nudging methods to initialise ice sheet model basal conditions. Geosci. Model Dev. 2016

Assimilation of friction at different dates:

• Gillet-Chaulet, F., Durand, G., Gagliardini, O., Mosbeux, C., Mouginot, J., Rémy, F., Ritz, C., 2016. Assimilation of surface velocities acquired between 1996 and 2010 to constrain the form of the basal friction law under Pine Island Glacier. Geophys. Res. Lett. 2016



SSA: See Oslo - 2016 Course



UiO - Oslo - 31st October, 1st and 2nd November 2016

The Department of Geosciences of the University of Oslo in cooperation with UGGE (France) and CSC (Finland) is organizing a 3-day beginner Elmer/Ice course on the 31st of October, 1st and 2nd of November 2016. This course is sponsored by the Labex OSUG@2020 and eScience tools for investigating climate change (SETICC).

Title	Presentation	Material
Introduction	📠 pdf	-
Toy flow-line model	📠 pdf	🔂 tar file
Tête Rousse	pdf	🝙 tar file
Ice flow and temperature coupling	pdf	📠 tar file
Inverse modelling and SSA	📠 pdf	🚾 tar file

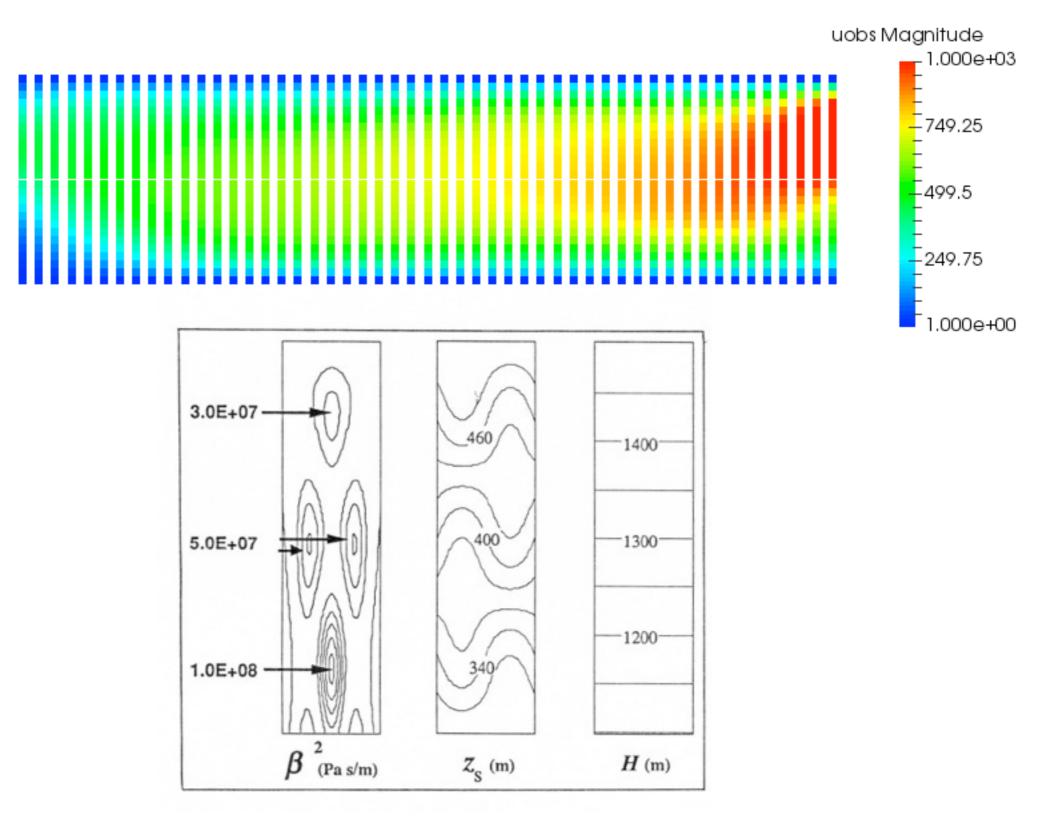
Download the list of participants, program and useful informations makere.







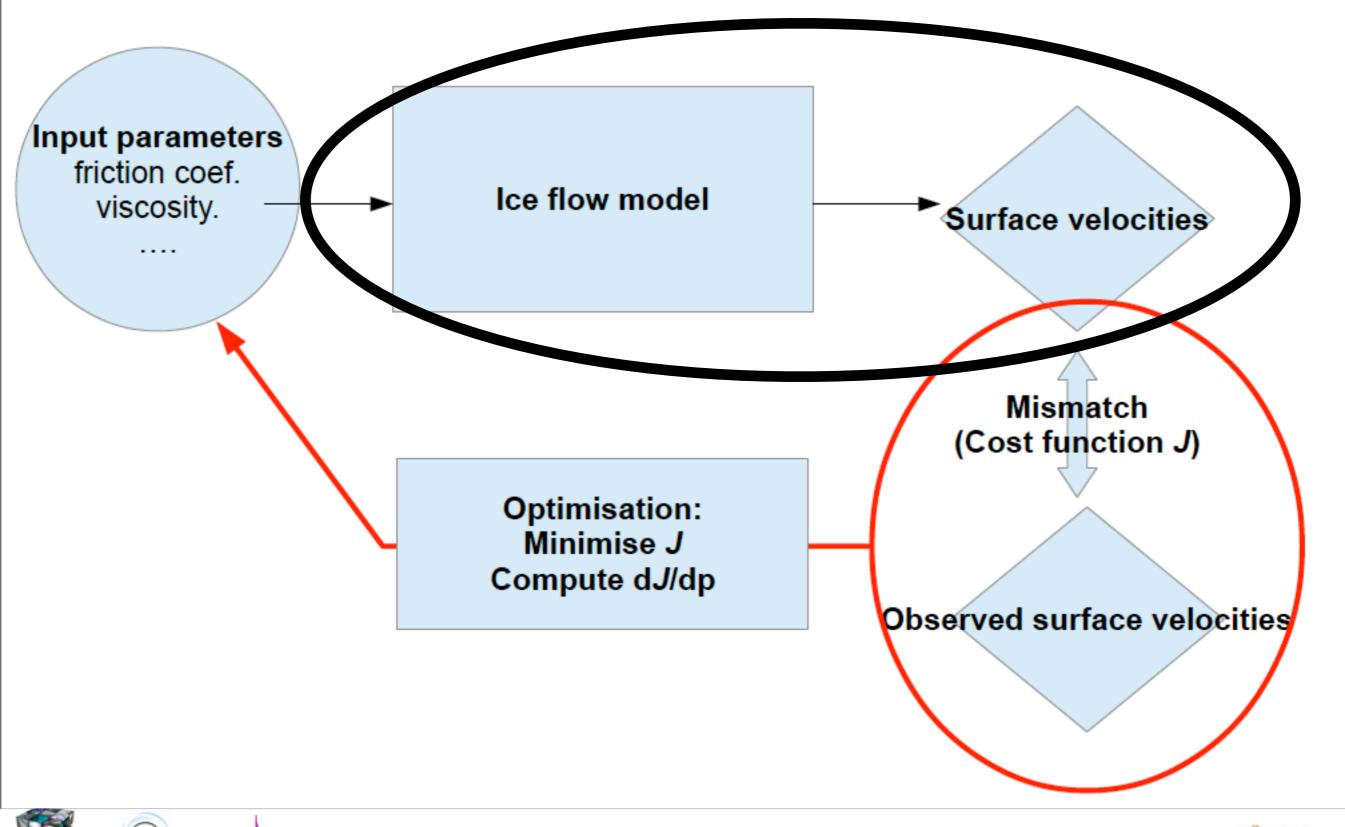
Repeat Mac Ayeal Twin Experiment







Variational data assimilation





Initial guess

the guess (square root of)

```
Initial Condition 1
```

```
alpha = Real 1.0e-3
```

```
Zb = Variable coordinate 1, Coordinate 2
    REAL MATC "zb(tx)"
```

```
Zs = Variable coordinate 1, Coordinate 2
    REAL MATC "zs(tx)"
```

```
SSAVelocity 1 = Real 0.0
SSAVelocity 2 = Real 0.0
End
```

the truth

```
$ function betaSquare(tx) {\
Lx = 200.0e3;\
Ly = 50.0e03;\
yearinsec = 365.25*24*60*60;\
F1=sin(3.0*pi*tx(0)/Lx)*sin(pi*tx(1)/Ly);\
F2=sin(pi*tx(0)/(2.0*Lx))*cos(4.0*pi*tx(1)/Ly);\
beta=5.0e3*F1+5.0e03*F2;\
_betaSquare=beta*beta/(1.0e06*yearinsec);\
```







Compute model velocity

Material 1

```
Viscosity Exponent = Real $1.0e00/3.0e00
Critical Shear Rate = Real 1.0e-10
SSA Mean Density = Real $rhoi
SSA Mean Viscosity = Real $ 1.8e8*1.0e-6*(2.0*yearinsec)^(-1.0/3.0)
SSA Friction Law = String "linear"
```

End

Solver 1

Equation = "SSA"
Variable = -dofs 2 "SSAVelocity"

Procedure = "AdjointSSASolvers" "AdjointSSA_SSASolver"

!! Mandatory for the adjoint
Calculate Loads = Logical True

```
Linear System Solver = Direct
Linear System Direct Method = mumps
```

```
Nonlinear System Max Iterations = 50
Nonlinear System Convergence Tolerance = 1.0e-10
Nonlinear System Newton After Iterations = 40
Nonlinear System Newton After Tolerance = 1.0e-06
Nonlinear System Relaxation Factor = 1.00
```

Steady State Convergence Tolerance = Real 1.0e-12

```
Exported Variable 1 = Zb
Exported Variable 2 = Zs
Exported Variable 3 = BetaS
Exported Variable 4 = CostValue
Exported Variable 5 = DJDBeta
Exported Variable 6 = -dofs 2 "Velocityb"
End
```

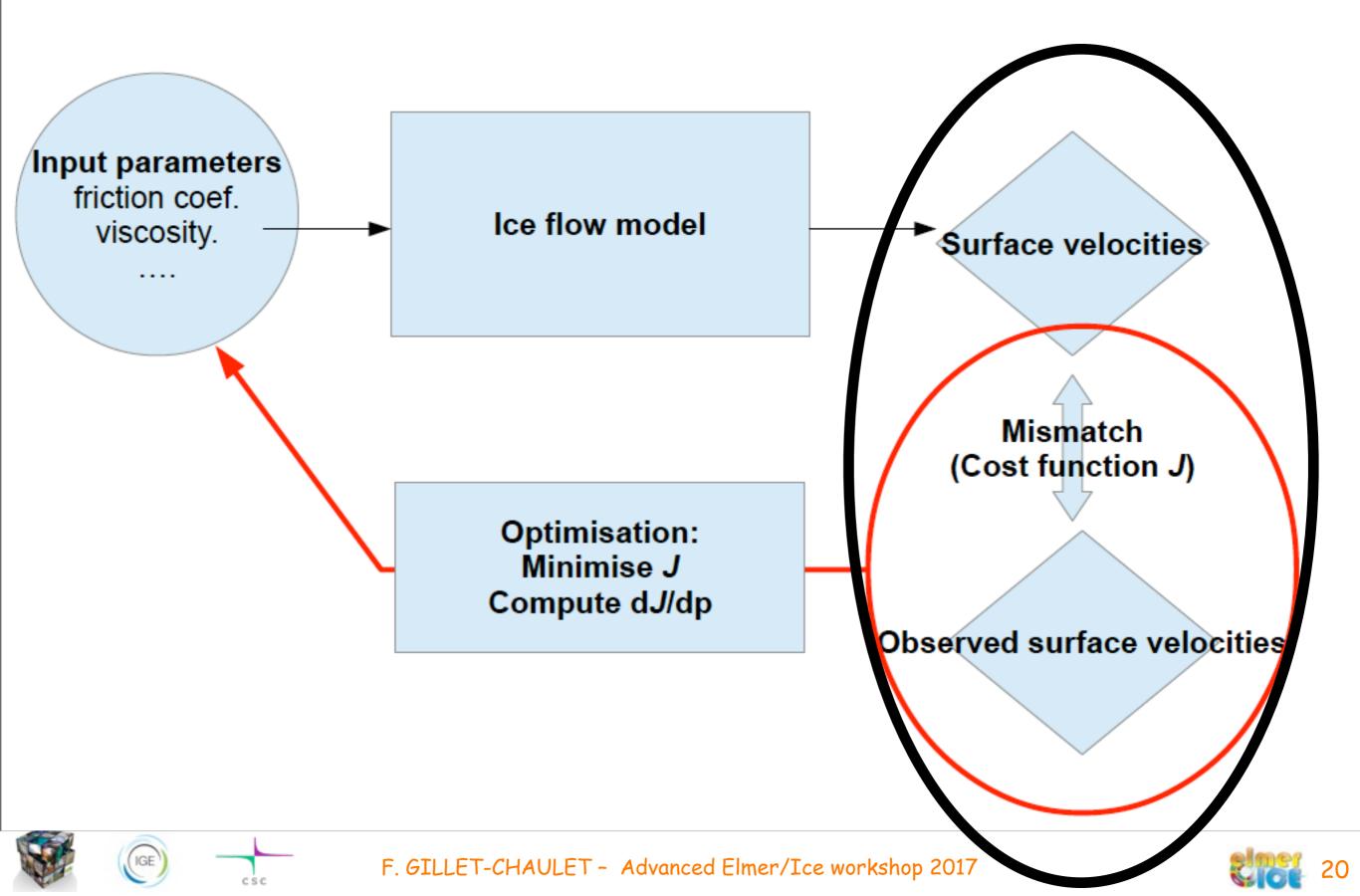
The direct solver used to make the adjoint (may not be up-to-date wr the latest ssa solver)

For the accuracy of the adjoint use Newton method for non-linear iterations

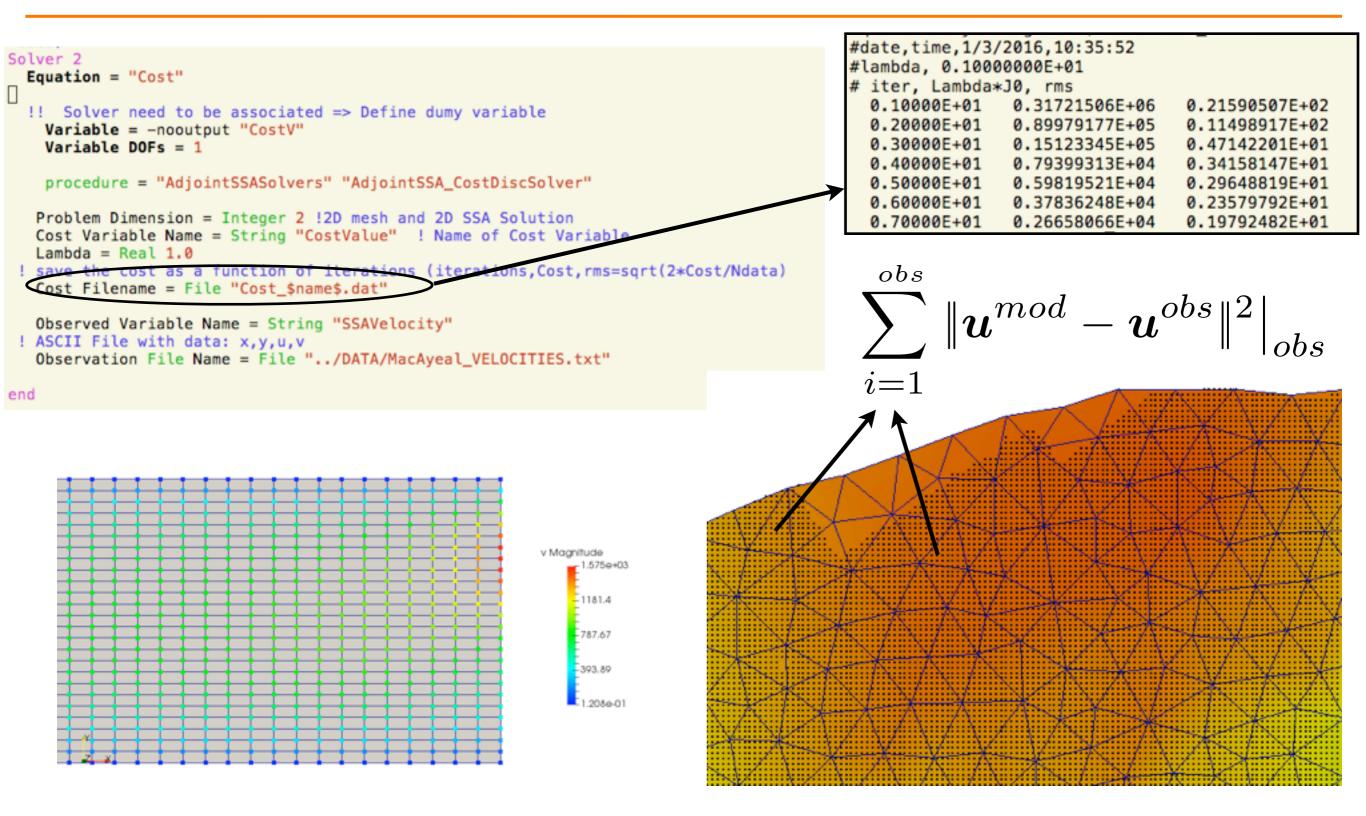








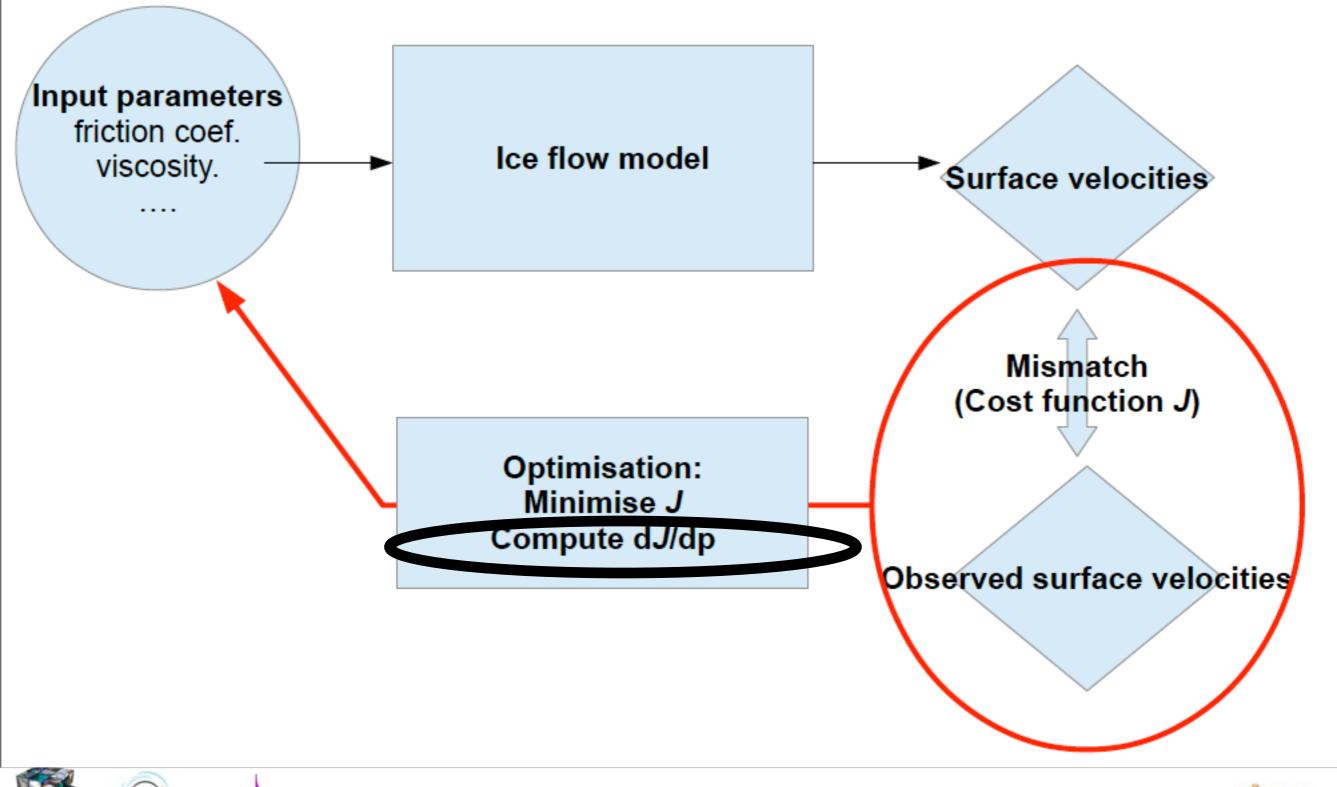
Compute the cost function



F. G



IGE





Compute the gradient

```
!!!! Adjoint Solution
Solver 3
 Equation = "Adjoint"
 Variable = Adjoint
 Variable Dofs = 2
 procedure = "AdjointSSASolvers" "AdjointSSA_AdjointSolver"
!Name of the flow solution solver
 Flow Solution Equation Name = string "SSA"
  Linear System Solver = Direct
  Linear System Direct Method = mumps
End
!!!!! Compute Derivative of Cost function / Beta
Solver 4
 Equation = "DJDBeta"
  !! Solver need to be associated => Define dumy variable
   Variable = -nooutput "DJDB"
    Variable DOFs = 1
   procedure = "AdjointSSASolvers" "AdjointSSA_GradientSolver"
   Flow Solution Name = String "SSAVelocity"
   Adjoint Solution Name = String "Adjoint"
   Compute DJDBeta = Logical True ! Derivative with respect to the Friction parameter
   DJDBeta Name = String "DJDBeta"
end
```





Boundary conditions

```
Boundary Condition 1
 Name = "Side Walls"
 Target Boundaries(2) = 13
 SSAVelocity 1 = Real 0.0
 SSAVelocity 2 = Real 0.0
 Adjoint 1 = Real 0.0
 Adjoint 2 = Real 0.0
End
Boundary Condition 2
 Name = "Inflow"
 Target Boundaries = 4
  SSAVelocity 1 = Variable Coordinate 2
     REAL MATC "4.753e-6*yearinsec*(sin(2.0*pi*(Ly-tx)/Ly)+2.5*sin(pi*(Ly-tx)/Ly))"
  SSAVelocity 2 = Real 0.0
 Adjoint 1 = Real 0.0
 Adjoint 2 = Real 0.0
End
Boundary Condition 3
 Name = "OutFlow"
 Target Boundaries = 2
  SSAVelocity 1 = Variable Coordinate 2
     REAL MATC "1.584e-5*yearinsec*(sin(2.0*pi*(Ly-tx)/Ly)+2.5*sin(pi*(Ly-tx)/Ly)+0.5*sin(3.0*pi*(Ly-tx)/Ly))"
  SSAVelocity 2 = Real 0.0
 Adjoint 1 = Real 0.0
 Adjoint 2 = Real 0.0
End
```



Change of variable

We have computed the gradient wr to the friction parameter; physically this parameter should remain positive => make change of variable $\beta = \alpha^2$ or $\beta = 10^{\alpha}$

```
Solver 5
Equation = "UpdateExport"
    Procedure = File "ElmerIceSolvers" "UpdateExport"
    Variable = -nooutput "dumy"
!used here to update DJDalpha from DJDbeta (see correponding line in Body Force section)
    Exported Variable 1 = -dofs 1 alpha
    Exported Variable 2 = -dofs 1 DJDalpha
End
```

```
Body Force 1
Flow BodyForce 1 = Real 0.0
Flow BodyForce 2 = Real 0.0
Flow BodyForce 3 = Real $gravity
! change of variable; DJDBeta is the derivative of the Cost fn w.r.t. the slip coeff.
! as slip coeff=alpha^2 => DJDalpha=DJDBeta * DBeta / Dalpha
DJDalpha = Variable DJDBeta , alpha
REAL MATC "2.0*tx(0)*tx(1)"
End
```

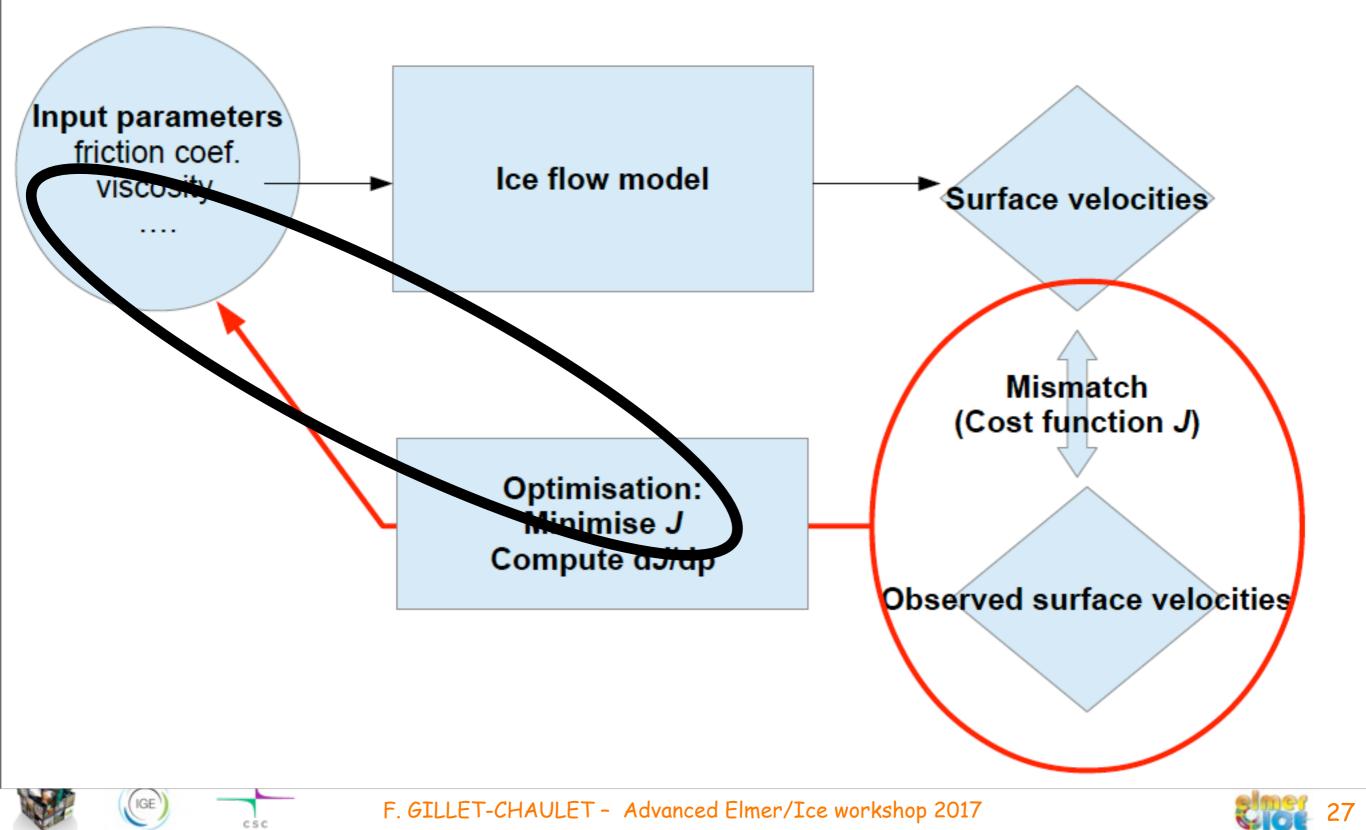






!!!!! Compute Regularistaion term Regularisation by default is: Lambda * int_{Pb dimension} 0.5 * (d(var)/dx)**2 A priori regularisation can also be used (A priori Regularisation=True) : Lambda * int_{Pb dimension} 0.5 *(1/sigma**2)*(var-var{a_priori})**2 OUTPUT are : J and DJDvar Solver 6 Equation = "DJDBeta_Reg" !! Solver need to be associated => Define dumy variable Variable = -nooutput "DJDBReg" Variable DOFs = 1 procedure = "AdjointSSASolvers" "AdjointSSA_CostRegSolver" Problem Dimension=Integer 2 Cost Filename=File "CostReg_\$name\$.dat" Optimized Variable Name= String "alpha" Gradient Variable Name= String "DJDalpha" Cost Variable Name= String "CostValue" Lambda= Real \$Lambda Reset Cost Value= Logical False !=> DJDapha already initialized in solver DJDBeta; switch off initialisation to 0 at the beginning of this solver A priori Regularisation= Logical False end #date,time,1/3/2016,10:35:52 Most real inverse problem are ill-posed #lambda, 0.00000000E+00 => add a-priori knowldedge to regularise the problem # iter, Jreq 0.10000E+01 0.96510928E-35 => not needed here as the obs. are perfect! 0.20000E+01 0.26697707E-06 0.30000E+01 0.91582437E-06 0.40000E+01 0.12325799E-05 0.50000E+01 0.14043708E-05 0.60000E+01 0.16939676E-05 0.70000E+01 0.22054452E-05





Optimisation

```
!!!!! Optimization procedure : Parallel only
Solver 7
  Equation = "Optimize_m1qn3"
  !! Solver need to be associated => Define dumy variable
   Variable = -nooutput "UB"
   Variable DOFs = 1
 procedure = "ElmerIceSolvers" "Optimize_m1qn3Parallel"
 Cost Variable Name = String "CostValue"
  Optimized Variable Name = String "alpha"
 Gradient Variable Name = String "DJDalpha"
 gradient Norm File = File "GradientNormAdjoint_$name$.dat"
 ! M10N3 Parameters
 M10N3 dxmin = Real 1.0e-10
                                                            #10/31/2016
                                                                            10:35:52
 M1QN3 epsg = Real 1.e-5
                                                              0.10000E+01
                                                                            0.84790499E+08
 M1QN3 niter = Integer 200
                                                              0.20000E+01
                                                                            0.38736142E+08
 M1QN3 nsim = Integer 200
                                                              0.30000E+01
                                                                            0.97311488E+07
 M1QN3 impres = Integer 5
                                                              0.40000E+01
                                                                            0.34591176E+07
 M1QN3 DIS Mode = Logical False
                                                              0.50000E+01
                                                                            0.27595369E+07
 M1QN3 df1 = Real 0.5
                                                              0.60000E+01
                                                                            0.21367979E+07
 M1QN3 normtype = String "dfn"
                                                              0.70000E+01
                                                                            0.89028275E+06
 M1QN3 OutputFile = File "M1QN3 $name$.out"
                                                              0.80000E+01
                                                                            0.99144675E+06
 M1QN3 ndz = Integer 20
                                                              0.90000E+01
                                                                            0.20111705E+07
```

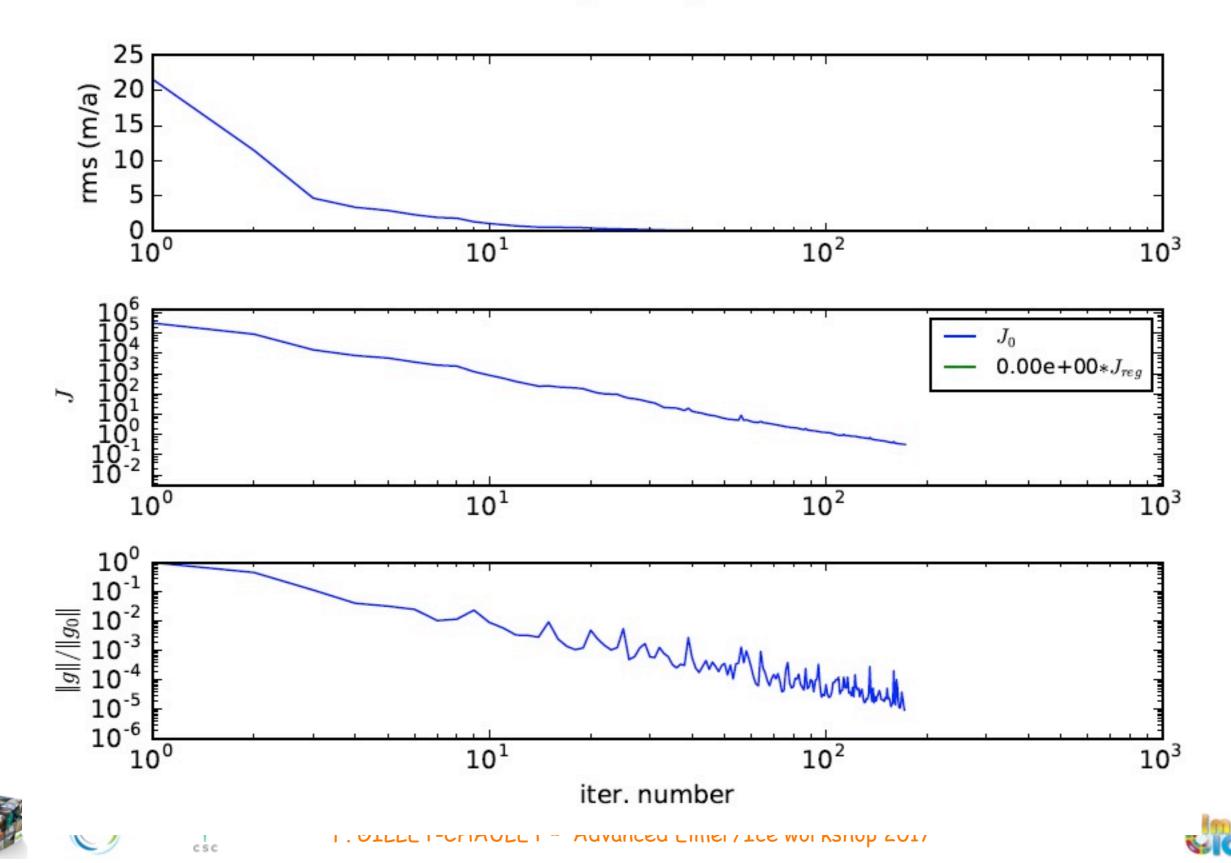
end





Check the convergence!!

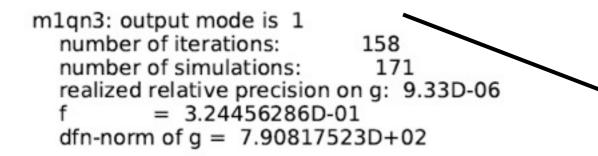
Convergence plots



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Output information

M1QN3 last 7 lines



M1QN3 documentation

omode (O): Integer variable that specifies the output mode of m1qn3. The following values are meaningful.

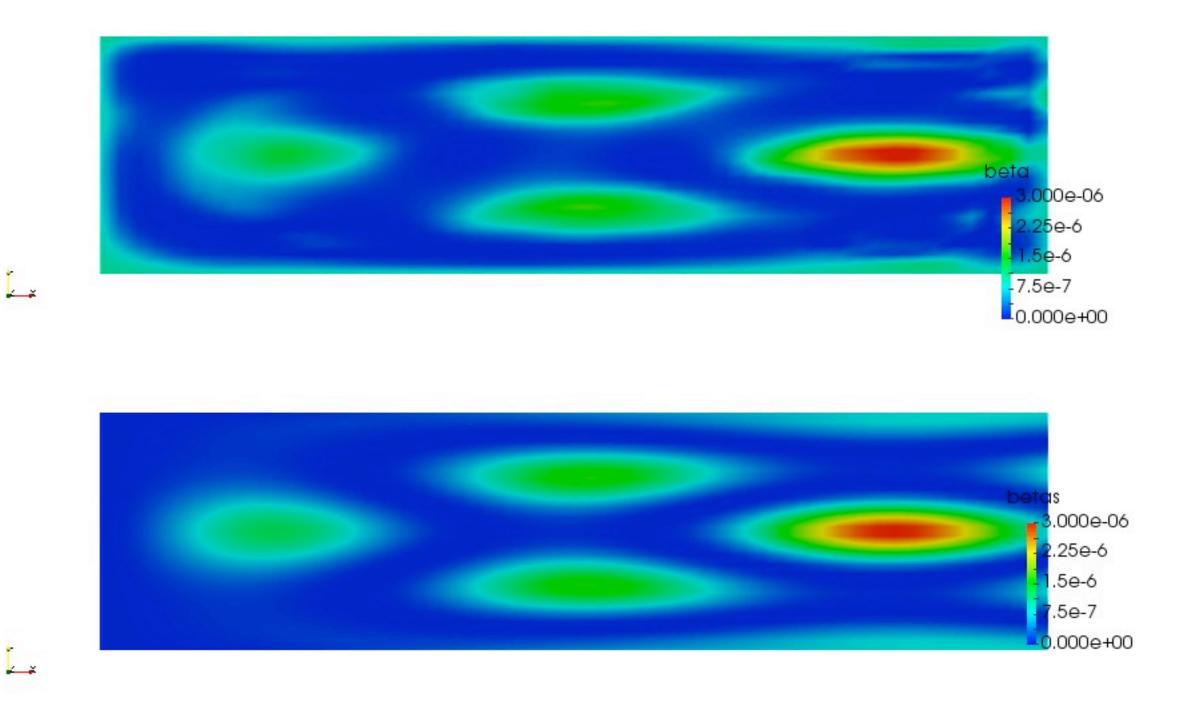
- = 0: The simulator asks to stop by returning the value indic = 0.
- = 1: This is the normal way of stopping for m1qn3: the test on the gradient is satisfied (see the meaning of epsg).
- = 2: One of the input arguments is not well initialized. This can be:
 - $-n \le 0$, niter ≤ 0 , nsim ≤ 0 , dxmin ≤ 0.0 or epsg $\notin]0, 1[$,
 - ndz <5n+1 (in SIS mode) or ndz <6n+1 (in DIS mode): not enough storage in memory,
 - the contents of iz is not correct for a warm restart,
 - the starting point is almost optimal (the norm of the initial gradient is less than 10⁻²⁰).
- = 3: The line-search is blocked on tmax = 10²⁰ (see section 4.4 and the documentation on mlis3 in MODULOPT library).
- = 4: The maximal number of iterations is reached.
- = 5: The maximal number of simulations is reached.
- = 6: Stop on dxmin during the line-search (see section 4.4).
- = 7: Either $\langle g, d \rangle$ is nonnegative or $\langle y, s \rangle$ is nonpositive (see section 4.4).

For additional information and comments, see section 4.





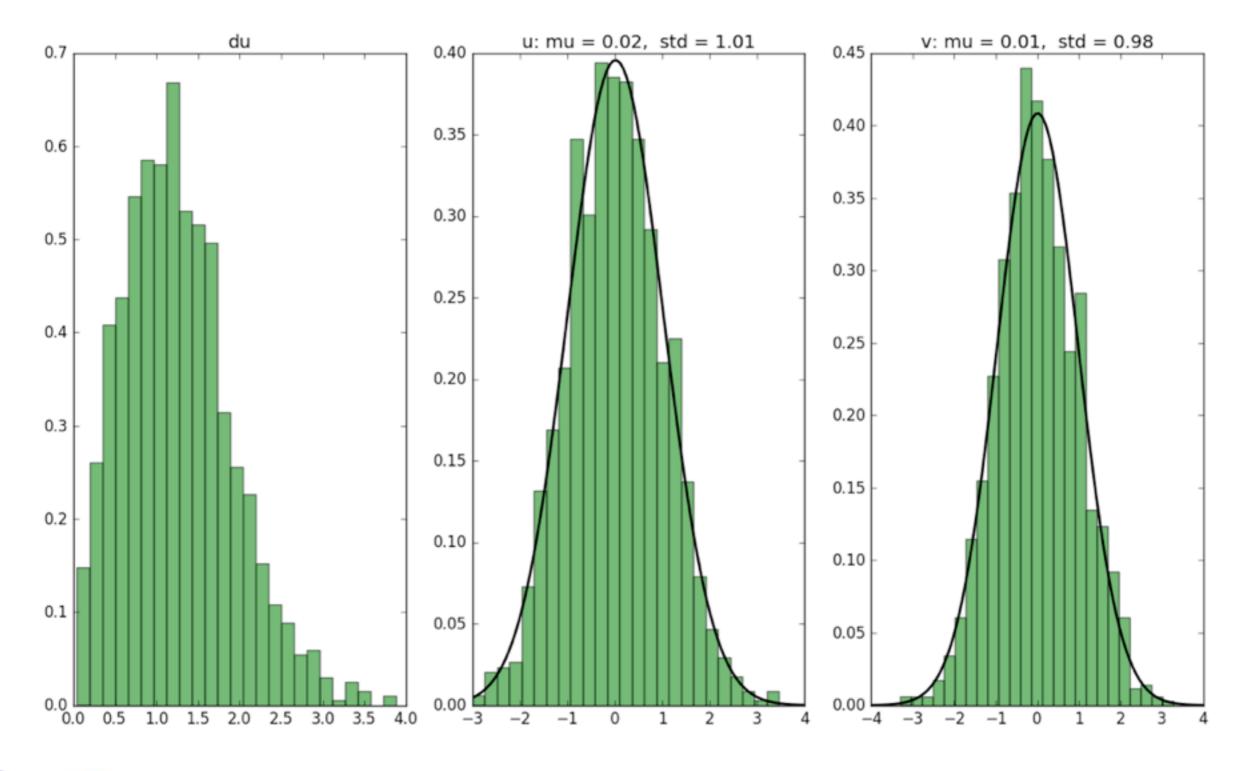
csc







Add noise in the data





IGE

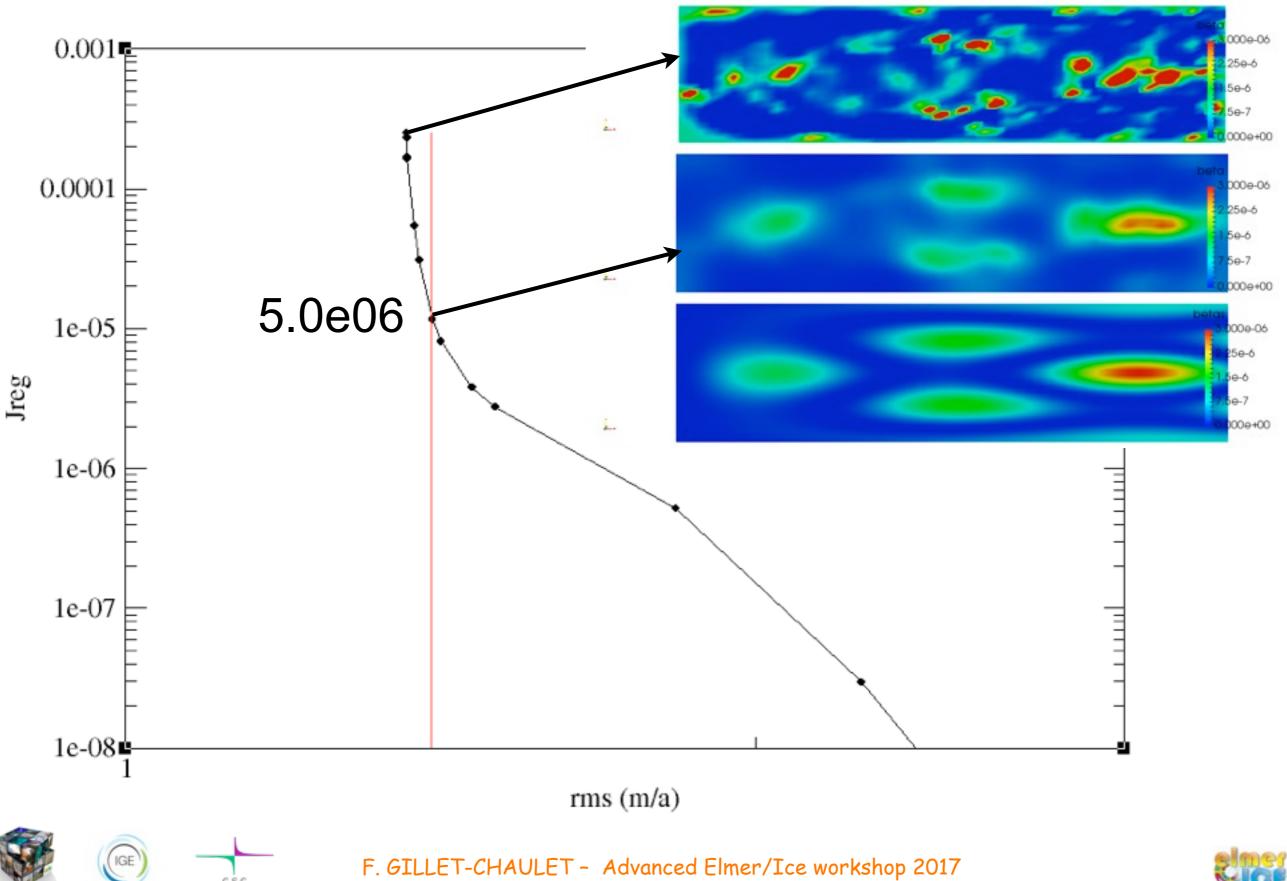
csc





Plot a L-Curve

csc

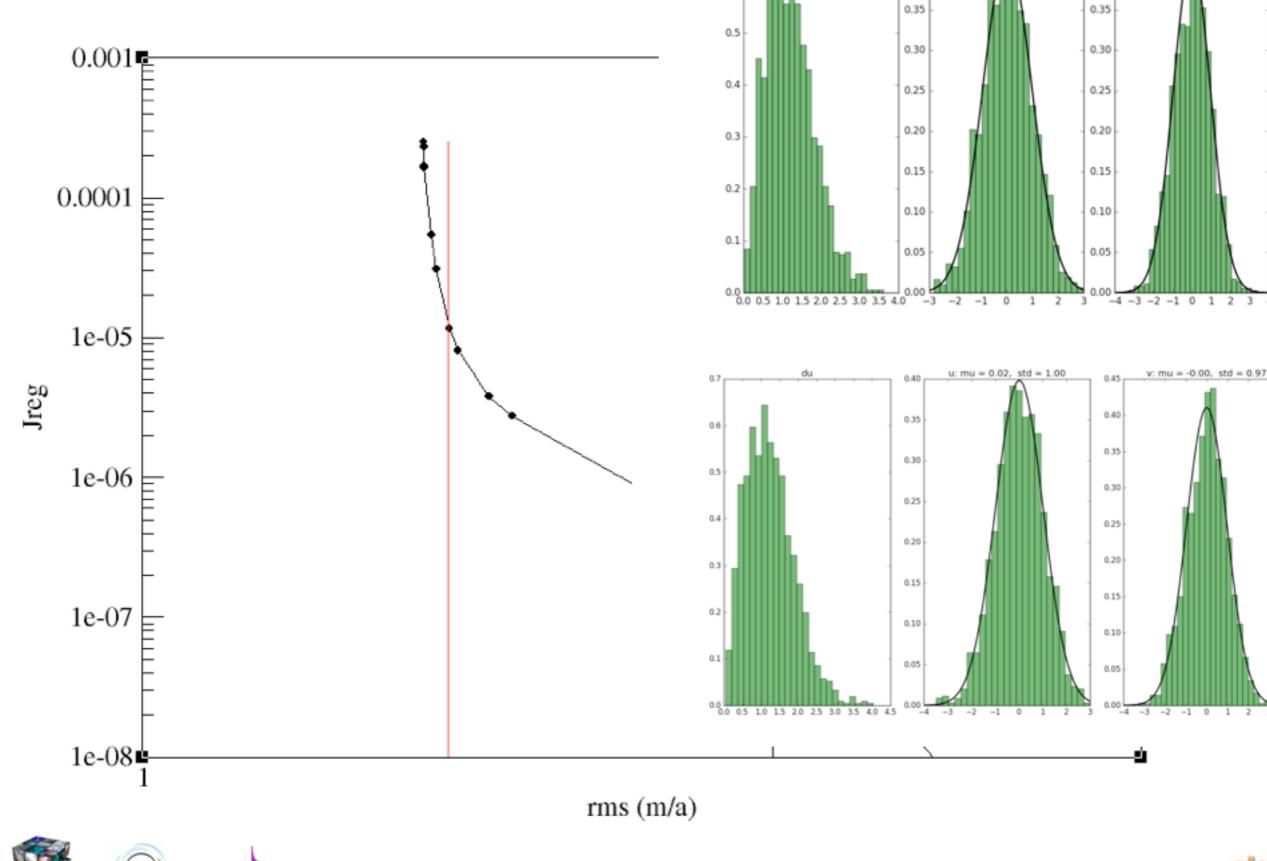


33

Plot a L-Curve

IGE

csc



du

0.45

0.40

0.7

0.6

F. GILLET-CHAULET - Advanced Elmer/Ice workshop 2017



0.45 v: mu = -0.01, std = 0.96

2 3 4

1

-1

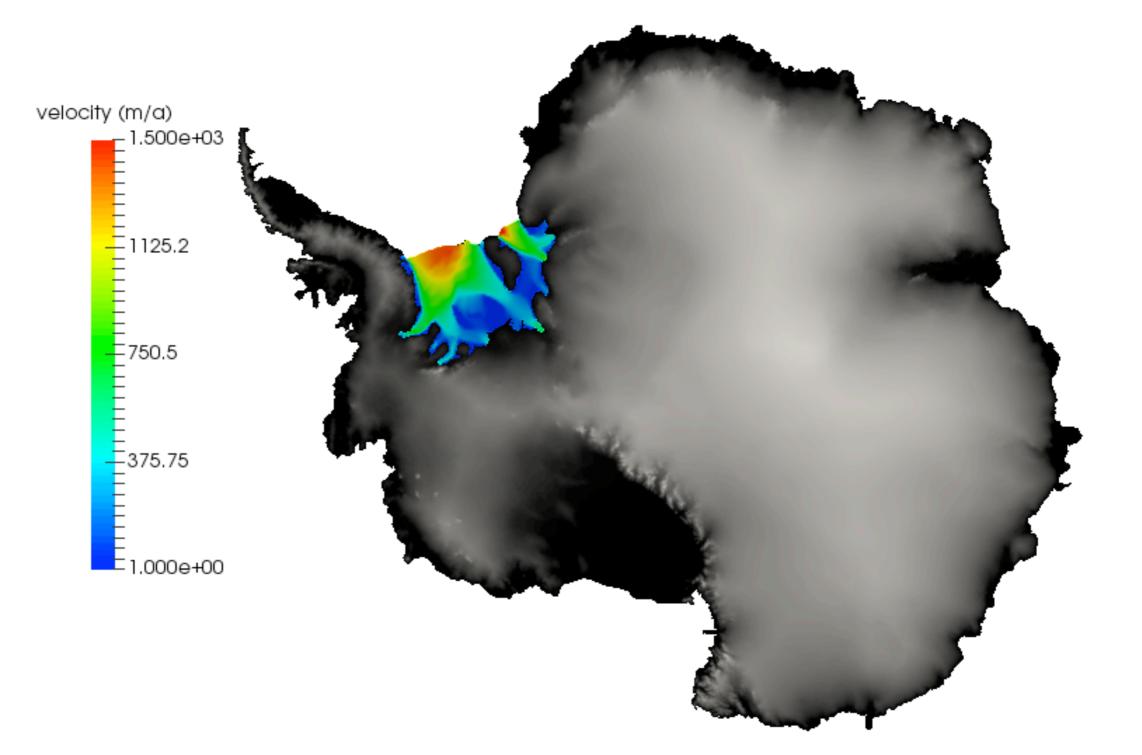
0

1 2

0.40

u: mu = 0.03, std = 0.96

Model Ronne-Filchner Ice Shelf







```
Simulation
Coordinate System = Cartesian
Simulation Type = Steady State
Steady State Min Iterations = 1
Steady State Max Iterations = 200
Post File = "OPTIM_$name$.vtu"
Restart File = "IMPORT.result"
Restart Before Initial Conditions = logical True
max output level = 3
End
```

I have already imported data required for the computation

```
Initial Condition 1
! alpha is the optimised variable
  alpha = Variable Mu
     REAL MATC "sqrt(tx)"
End
```





Optimise mean viscosity

```
Viscosity Exponent = Real $1.0e00/3.0e00
Critical Shear Rate = Real 1.0e-10
```

```
SSA Mean Density = Real $rhoi
SSA Mean Viscosity = Variable alpha
REAL procedure "Adjoint_USFs" "Asquare"
SSA Friction Law = String "linear"
SSA Friction Parameter = Real 0.0
End
```

```
!!!!!! Compute Derivative of Cost function / Beta
Solver 4
Equation = "DJDEta"
!! Solver need to be associated => Define dumy variable
Variable = -nooutput "DJDB"
Variable DOFs = 1
procedure = "AdjointSSASolvers" "AdjointSSA_GradientSolver"
Flow Solution Name = String "SSAVelocity"
Adjoint Solution Name = String "Adjoint"
Compute DJDEta = Logical True ! Derivative with respect to the SSA Mean Viscosity
```

end







Boundary conditions

```
Boundary Condition 1
Target Boundaries(2) = 1 3
SSAVelocity 1 = Equals Uobs 1
SSAVelocity 2 = Equals Uobs 2
Adjoint 1 = Real 0.0
Adjoint 2 = Real 0.0
End
Boundary Condition 2
Name = "Ice Front"
Target Boundaries(2) = 2 4
calving front = logical true
End
```



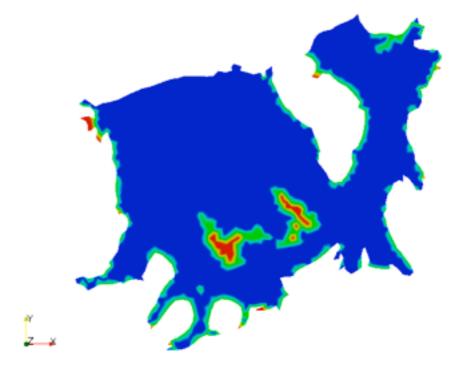


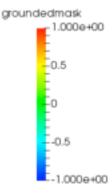




Apply Dirichlet condition in grounded parts

```
Body Force 1
 Flow BodyForce 1 = Real 0.0
 Flow BodyForce 2 = Real 0.0
 Flow BodyForce 3 = Real $gravity
 DJDalpha = Variable DJDEta , alpha
    REAL procedure "Adjoint_USFs" "Derivative_Asquare"
 SSAVelocity 1 = Equals Uobs 1
 SSAVelocity 2 = Equals Uobs 2
 SSAVelocity 1 Condition = Variable GroundedMask
   Real procedure "USFs_RonneFilchner" "GM_CONDITION"
 SSAVelocity 2 Condition = Variable GroundedMask
   Real procedure "USFs RonneFilchner" "GM CONDITION"
 Adjoint 1 = Real 0.0
  Adjoint 2 = Real 0.0
 Adjoint 1 Condition = Variable GroundedMask
   Real procedure "USFs_RonneFilchner" "GM_CONDITION"
 Adjoint 2 Condition = Variable GroundedMask
   Real procedure "USFs_RonneFilchner" "GM_CONDITION"
```





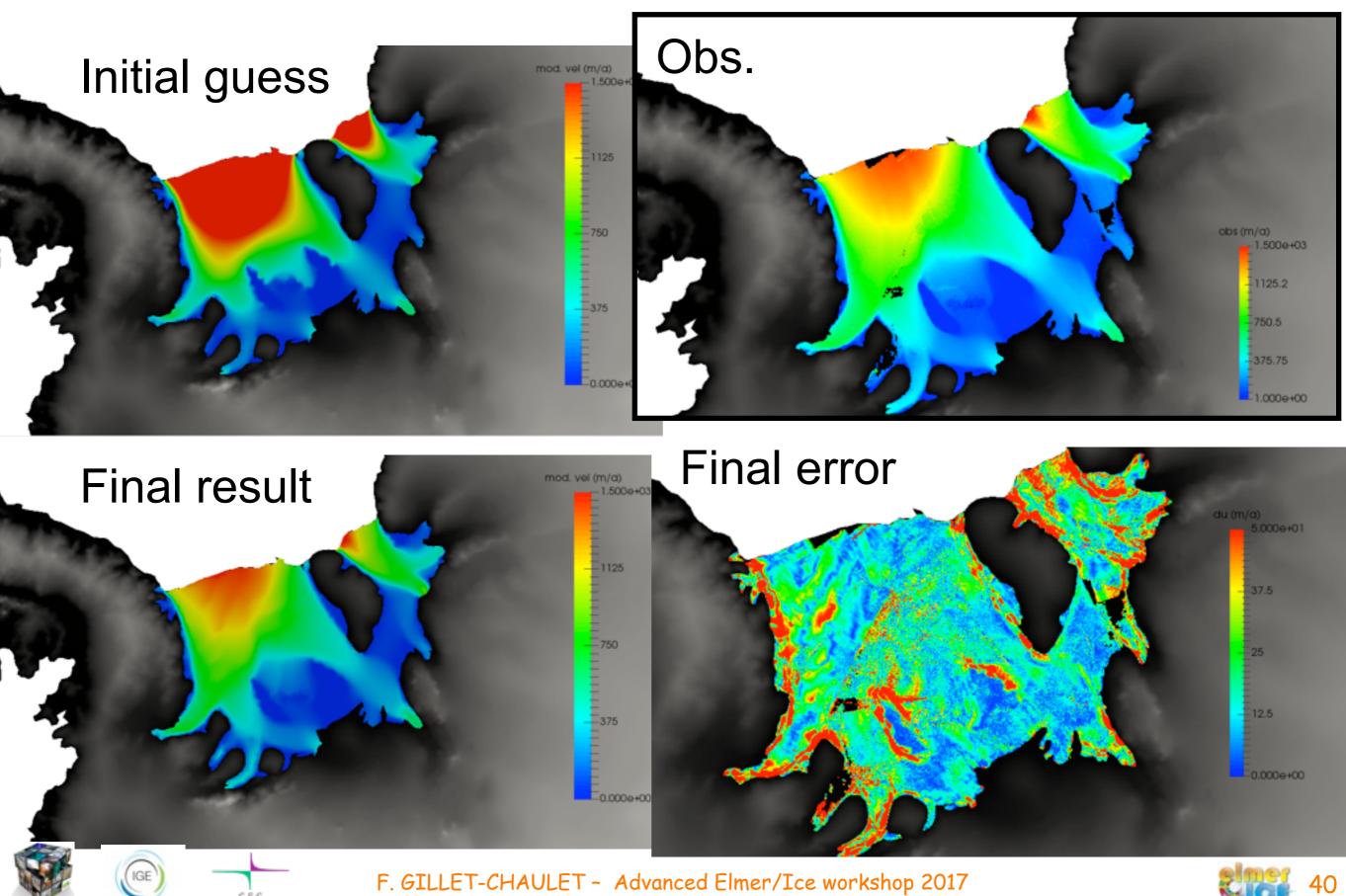


End

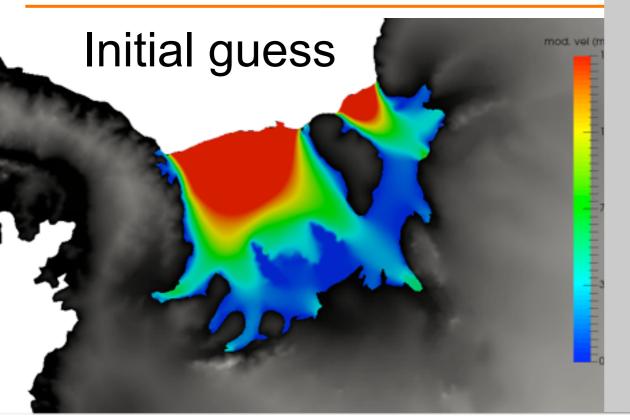


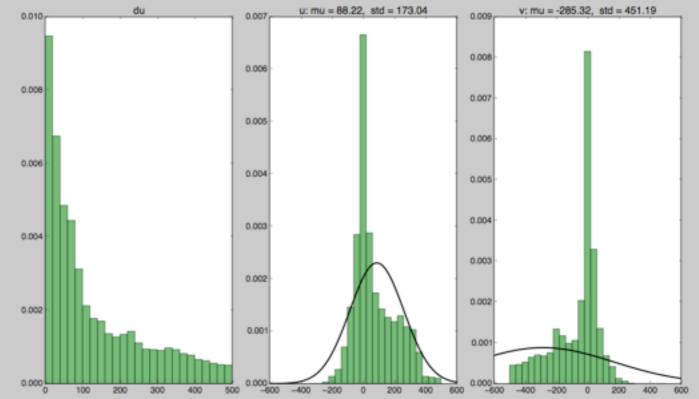
Results

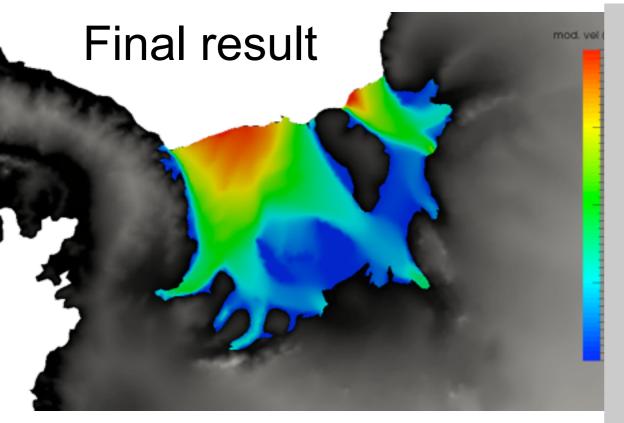
csc



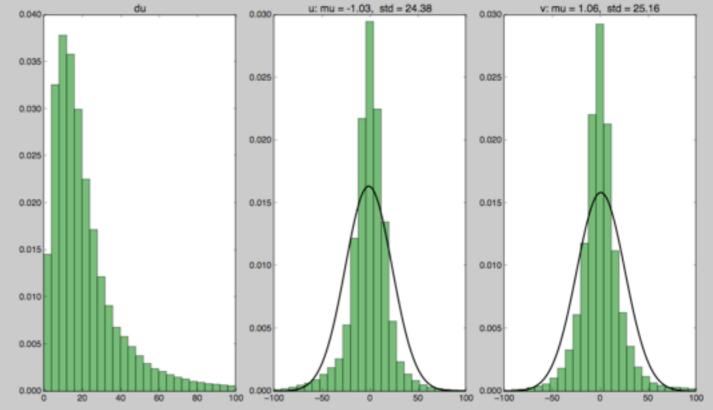
Results







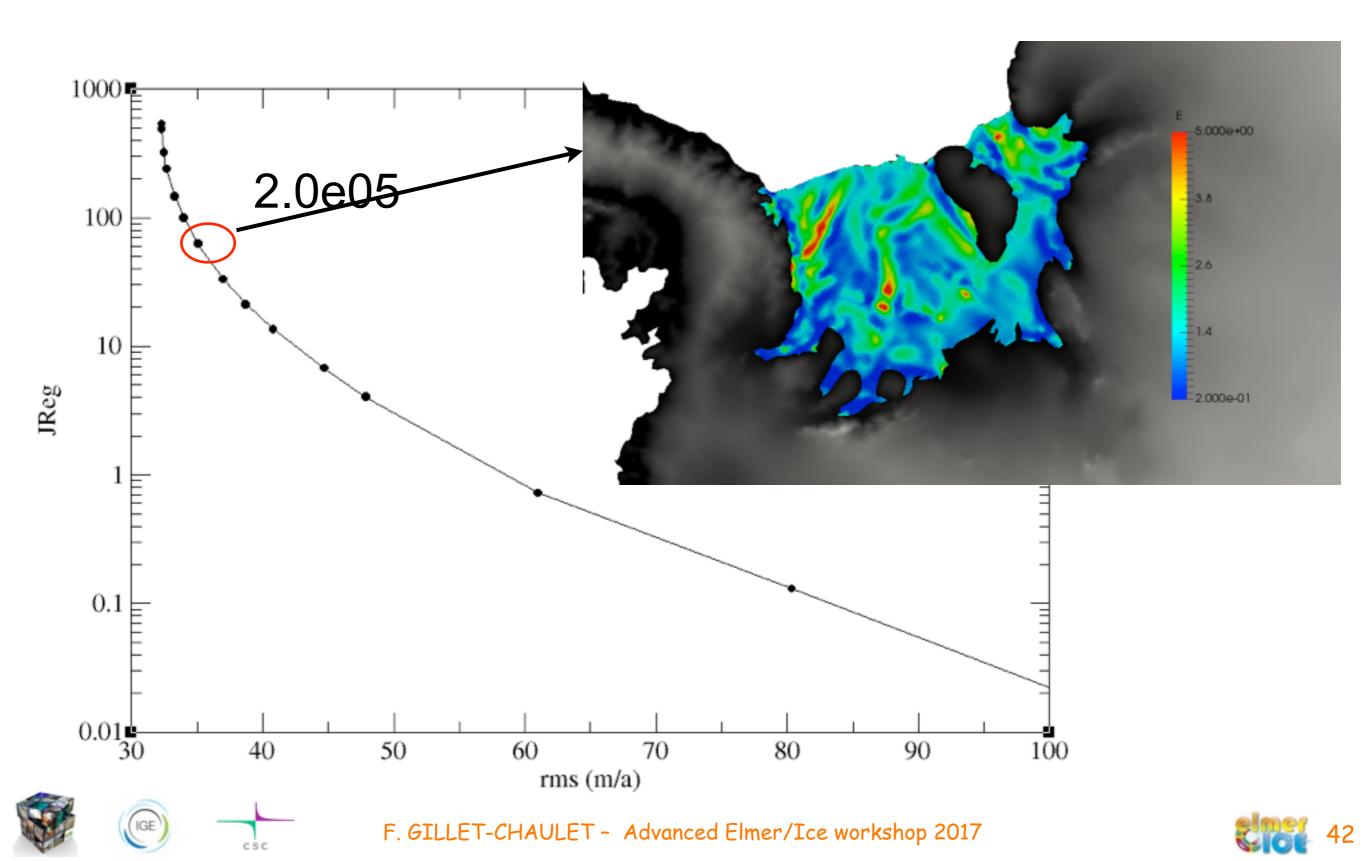
CSC







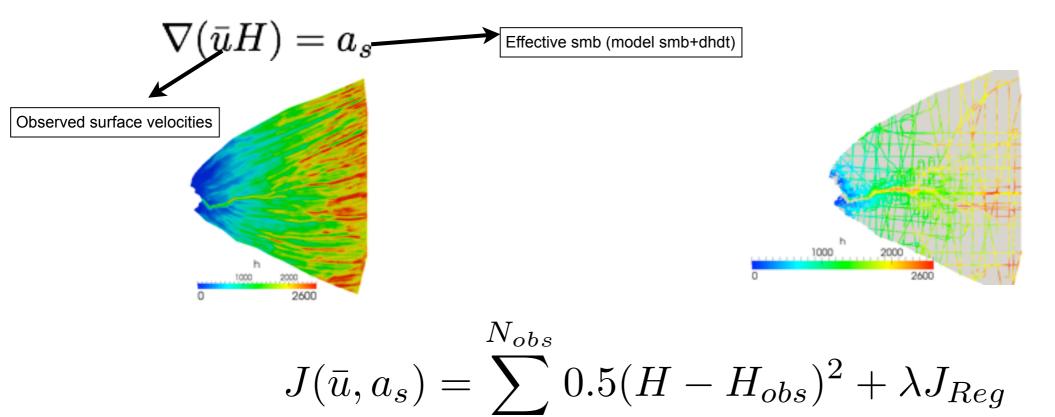
Results



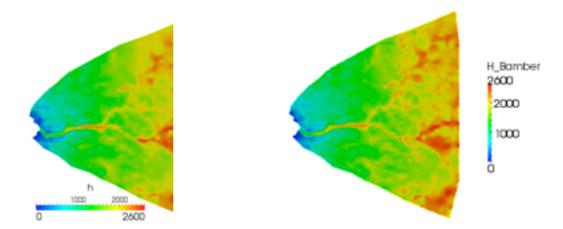
Inverse methods in Elmer: Thickness Solver

see Morlighem *et al.*, 2011, a mass consservation approach for mapping glacier ice thickness

1. Compute the blance thickness



3. Use the adjoint to optimise u and ^{1}a and reduced mismatch









2. Compare with observations

Inverse methods in Elmer: Thickness Solver

- Work already done
- See presentation by J. Fürst for more details
- Still requires some cleaning/re-arrangement before submission to the Elmer/Ice distrib.



